

## MAX32662

## Arm Cortex-M4 Processor with FPU-Based Microcontroller (MCU) with 256KB Flash and 80KB SRAM

### General Description

In the DARWIN family, the MAX32662 is an ultra-low-power, cost-effective, highly integrated 32-bit microcontroller designed for small battery-powered devices. It combines a flexible peripheral and feature mix with the powerful Arm® Cortex®-M4 processor with floating point unit (FPU) in a small form factor.

The MAX32662 enables complex edge-based designs without compromising battery life, and it also offers legacy designs an easy and cost optimal upgrade path from 8- or 16-bit microcontrollers.

Integrating 256KB of flash memory and 80KB of SRAM, the MAX32662 easily accommodates sensor code and complex algorithms.

Peripherals include SPI, UART, I<sup>2</sup>C, I<sup>2</sup>S, CAN 2.0B, and a 12-bit ADC.

A ROM-based secure bootloader uses 256-bit elliptic curve digital signature algorithm (ECDSA-256) encryption to ensure trusted and authenticated updates of customer software.

The device is available in a 5mm x 5mm, 32-pin TQFN-EP.

### Applications

- Sports Watches
- Fitness Monitors
- Wearable Medical Patches
- Portable Medical Devices
- Industrial Sensors
- IoT

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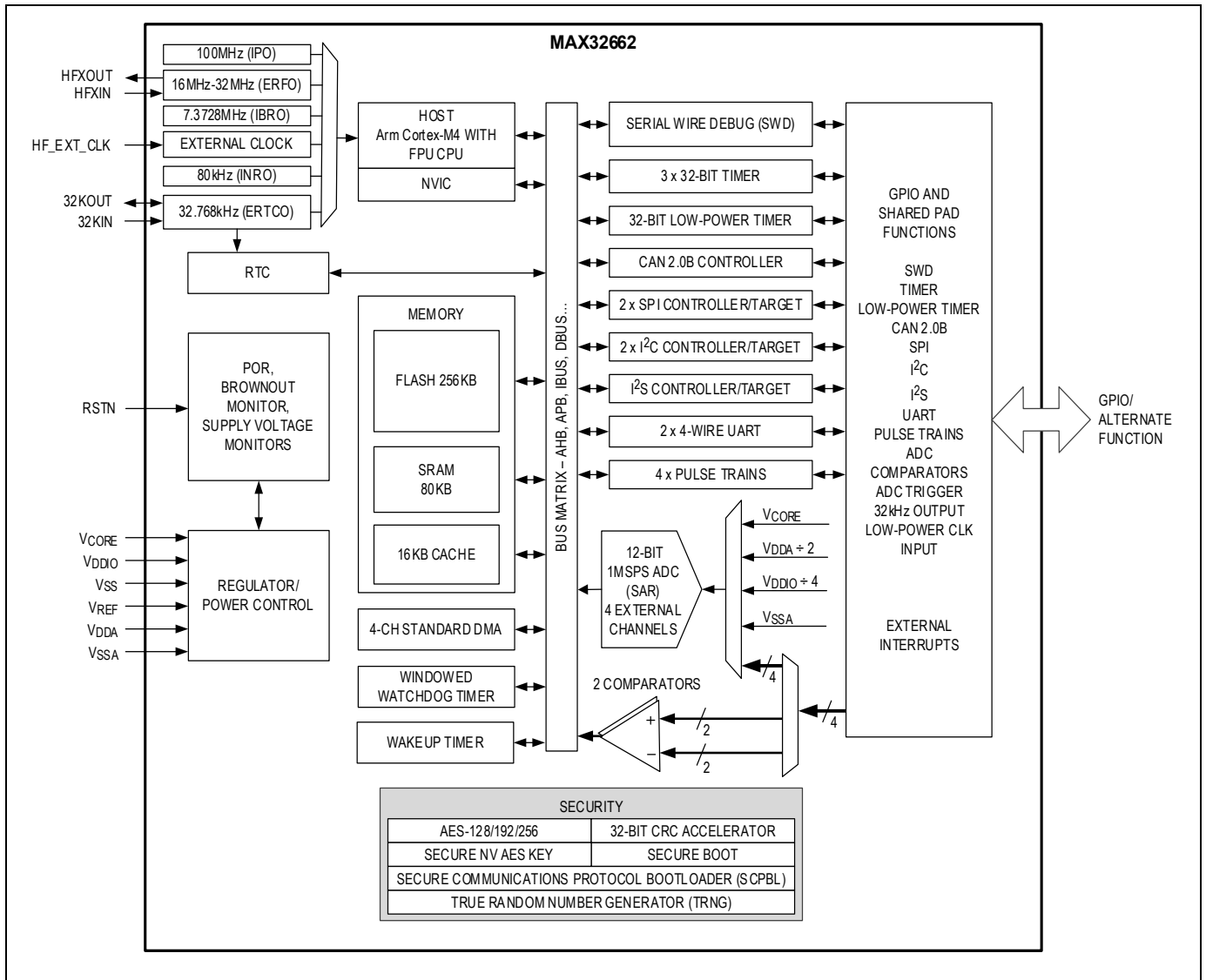
### Benefits and Features

- High-Efficiency Microcontroller for Low-Power, High-Reliability Devices
  - 256KB Flash
  - 80KB SRAM, Optionally Preserved in Lowest Power BACKUP Mode
  - 16KB Unified Cache
  - Memory Protection Unit (MPU)
  - Dual- or Single-Supply Operation: 1.7V to 3.6V
  - Wide Operating Temperature: -40°C to +105°C
- Flexible Clock Sources
  - Internal High-Speed 100MHz
  - Internal Low-Power 7.3728MHz
  - Ultra-Low-Power 80kHz
  - 16MHz–32MHz (External Crystal Required)
  - 32.768kHz (External Crystal Required)
  - External Clock Inputs for CPU and Low-Power Timer
- Power Management Maximizes Uptime for Battery Applications
  - 50µA/MHz at 0.9V up to 12MHz (CoreMark®) in ACTIVE Mode
  - 44µA/MHz at 1.1V up to 100MHz (While(1)) in ACTIVE Mode
  - 2.15µA Full Memory Retention Current in BACKUP Mode at V<sub>DDIO</sub> = 1.8V
  - 2.4µA Full Memory Retention Current in BACKUP Mode at V<sub>DDIO</sub> = 3.3V
  - 350nA Ultra-Low-Power RTC
  - Wakeup from Low-Power Timer
- Optimal Peripheral Mix Provides Platform Scalability
  - Up to 21 General-Purpose I/O Pins
  - 4-Channel, 12-Bit, 1Msps ADC
  - Two SPI Controller/Target
  - One I<sup>2</sup>S Controller/Target
  - Two 4-Wire UART
  - Two I<sup>2</sup>C Controller/Target
  - One CAN 2.0B Controller
  - 4-Channel Standard DMA Controller
  - Three 32-Bit Timers
  - One 32-Bit Low-Power Timer
  - One Watchdog Timer
  - CMOS-Level 32.768kHz Calibration Output
  - AES-128/192/256 Hardware Accelerator

**Ordering Information appears at end of data sheet.**

# Arm Cortex-M4 Processor with FPU- Based Microcontroller (MCU) with 256KB Flash and 80KB SRAM

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## TABLE OF CONTENTS

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General Description .....	1
Applications.....	1
Benefits and Features.....	1
Absolute Maximum Ratings .....	7
Package Information .....	7
Electrical Characteristics.....	8
Electrical Characteristics – I <sup>2</sup> C .....	39
Electrical Characteristics – I <sup>2</sup> S .....	41
Electrical Characteristics – SPI.....	42
Timing Diagrams.....	43
Pin Configuration – 20 WLP.....	46
Pin Descriptions – 20 WLP .....	46
Pin Configuration – 32 TQFN.....	49
Pin Descriptions – 32 TQFN .....	49
Detailed Description .....	53
Arm Cortex-M4 Processor with FPU Engine .....	53
Memory .....	53
Internal Flash Memory .....	53
Internal SRAM .....	53
Clocking Scheme .....	53
General-Purpose I/O and Special Function Pins.....	55
Standard DMA Controller .....	55
Power Management .....	55
Power Management Unit .....	55
Operating Modes .....	55
ACTIVE.....	55
SLEEP .....	56
DEEPSLEEP .....	56
BACKUP .....	56
STORAGE .....	56
Wake-Up Sources .....	57
Real-Time Clock (RTC).....	57
Windowed Watchdog Timer (WDT).....	57
32-Bit Timer/Counter/PWM .....	58
Serial Peripherals .....	58
Controller Area Network (CAN) 2.0B .....	58
I <sup>2</sup> C Interface .....	59

Serial Peripheral Interface (SPI) .....	59
I <sup>2</sup> S Interface .....	60
Universal Asynchronous Receiver Transmitter (UART) Interface.....	60
Analog-to-Digital Converter (ADC) .....	61
Security .....	61
AES.....	61
True Random Number Generator (TRNG) .....	61
CRC Module .....	61
Root of Trust .....	62
Secure Communications Protocol Bootloader (SCPBL).....	62
Secure Boot .....	62
Debug and Development Interface.....	62
Additional Documentation .....	62
Applications Information.....	62
Bootloader Activation .....	62
Bypass Capacitors .....	63
Typical Fixed Current Consumption Temperature Variance .....	64
Single-Supply ACTIVE Mode f <sub>SYS_OSC</sub> = IPO .....	64
Single-Supply SLEEP Mode f <sub>SYS_OSC</sub> = IPO.....	65
Single-Supply ACTIVE Mode f <sub>SYS_OSC</sub> = IBRO.....	66
Single-Supply SLEEP Mode f <sub>SYS_OSC</sub> = IBRO .....	67
Single-Supply DEEPSLEEP Mode .....	68
Single-Supply BACKUP Mode .....	69
Single-Supply STORAGE Mode .....	69
Dual-Supply ACTIVE Mode f <sub>SYS_OSC</sub> = IPO .....	70
Dual-Supply SLEEP Mode f <sub>SYS_OSC</sub> = IPO .....	71
Dual-Supply ACTIVE Mode f <sub>SYS_OSC</sub> = IBRO .....	72
Dual-Supply SLEEP Mode f <sub>SYS_OSC</sub> = IBRO.....	73
Dual-Supply DEEPSLEEP Mode .....	74
Dual-Supply BACKUP Mode .....	75
Dual-Supply STORAGE Mode.....	77
Typical Application Circuits .....	78
Ordering Information .....	79

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**LIST OF FIGURES**

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Figure 1. I <sup>2</sup> C Timing Diagram .....	43
Figure 2. I <sup>2</sup> S Controller Timing Diagram .....	43
Figure 3. I <sup>2</sup> S Target Timing Diagram.....	44
Figure 4. SPI Controller Mode Timing Diagram .....	44
Figure 5. SPI Target Mode Timing Diagram .....	45
Figure 6. Clocking Scheme Diagram .....	54

**LIST OF TABLES**

Table 1.	BACKUP Mode SRAM Retention.....	56
Table 2.	Wake-Up Sources .....	57
Table 3.	Timer Configuration Options .....	58
Table 4.	SPI Configuration Options.....	59
Table 5.	UART Configuration Options.....	60
Table 6.	Common CRC Polynomials .....	61
Table 7.	Bootloader Activation Summary.....	62
Table 8.	Single-Supply Operation Fixed $V_{DDIO}$ Current Consumption ACTIVE Mode $f_{SYS\_OSC} = IPO$ .....	64
Table 9.	Single-Supply Operation Fixed $V_{DDIO}$ Current Consumption SLEEP Mode $f_{SYS\_OSC} = IPO$ .....	65
Table 10.	Single-Supply Operation Fixed $V_{DDIO}$ Current Consumption ACTIVE Mode $f_{SYS\_OSC} = IBRO$ .....	66
Table 11.	Single-Supply Operation Fixed $V_{DDIO}$ Current Consumption SLEEP Mode $f_{SYS\_OSC} = IBRO$ .....	67
Table 12.	Single-Supply Operation Fixed $V_{DDIO}$ Current Consumption DEEPSLEEP Mode .....	68
Table 13.	Single-Supply Operation Fixed $V_{DDIO}$ Current Consumption BACKUP Mode .....	69
Table 14.	Single-Supply Operation Fixed $V_{DDIO}$ Current Consumption STORAGE Mode .....	69
Table 15.	Dual-Supply Operation Fixed $V_{CORE}$ Current Consumption ACTIVE Mode $f_{SYS\_OSC} = IPO$ .....	70
Table 16.	Dual-Supply Operation Fixed $V_{DDIO}$ Current Consumption ACTIVE Mode $f_{SYS\_OSC} = IPO$ .....	70
Table 17.	Dual-Supply Operation Fixed $V_{CORE}$ Current Consumption SLEEP Mode $f_{SYS\_OSC} = IPO$ .....	71
Table 18.	Dual-Supply Operation Fixed $V_{DDIO}$ Current Consumption SLEEP Mode $f_{SYS\_OSC} = IPO$ .....	71
Table 19.	Dual-Supply Operation Fixed $V_{CORE}$ Current Consumption ACTIVE Mode $f_{SYS\_OSC} = IBRO$ .....	72
Table 20.	Dual-Supply Operation Fixed $V_{DDIO}$ Current Consumption ACTIVE Mode $f_{SYS\_OSC} = IBRO$ .....	72
Table 21.	Dual-Supply Operation Fixed $V_{CORE}$ Current Consumption SLEEP Mode $f_{SYS\_OSC} = IBRO$ .....	73
Table 22.	Dual-Supply Operation Fixed $V_{DDIO}$ Current Consumption SLEEP Mode $f_{SYS\_OSC} = IBRO$ .....	73
Table 23.	Dual-Supply Operation Fixed $V_{CORE}$ Current Consumption DEEPSLEEP Mode.....	74
Table 24.	Dual-Supply Operation Fixed $V_{DDIO}$ Current Consumption DEEPSLEEP Mode .....	74
Table 25.	Dual-Supply Operation Fixed $V_{CORE}$ Current Consumption BACKUP Mode .....	75
Table 26.	Dual-Supply Operation Fixed $V_{DDIO}$ Current Consumption BACKUP Mode.....	75
Table 27.	Dual-Supply Operation Fixed $V_{CORE}$ Current Consumption STORAGE Mode .....	77
Table 28.	Dual-Supply Operation Fixed $V_{DDIO}$ Current Consumption STORAGE Mode .....	77

## Absolute Maximum Ratings

V <sub>CORE</sub> , HFXIN, HFXOUT .....	-0.2V to +1.21V	32 TQFN-EP Continuous Power Dissipation (Single Layer Board) (T <sub>A</sub> = +70°C, derate 21.28 mW/°C above +70°C.)	1170.2mW
V <sub>DDIO</sub> , V <sub>DDA</sub> .....	-0.3V to +3.63V	32 TQFN-EP Continuous Power Dissipation (Multilayer Board) (T <sub>A</sub> = +70°C, derate 27.8mW/°C above +70°C.)	1527.8mW
32KIN, 32KOUT, RSTN, GPIO ( <a href="#">Note 1</a> )	-0.3V to V <sub>DDIO</sub> + 0.3V	20 WLP Continuous Power Dissipation (Multilayer Board) (T <sub>A</sub> = +70°C, derate 18.02 mW/°C above +70°C.)	1441.7mW
Total Current into All GPIO Combined (sink)	100mA	Operating Temperature Range	-40°C to +105°C
V <sub>SS</sub> , V <sub>SSA</sub> .....	100mA	Storage Temperature Range	-65°C to +125°C
Output Current (sink) by Any GPIO Pin	25mA	Soldering Temperature (reflow)	+260°C
Output Current (source) by Any GPIO Pin	-25mA		

**Note 1:** No device pin can exceed 3.63V. All voltages with respect to V<sub>SS</sub>, unless otherwise noted.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## Package Information

### 32 TQFN-EP

Package Code	T3255+6C
Outline Number	<a href="#">21-0140</a>
Land Pattern Number	<a href="#">90-0630</a>
<b>Thermal Resistance, Single-Layer Board</b>	
Junction to Ambient (θ <sub>JA</sub> )	47°C/W
Junction to Case (θ <sub>JC</sub> )	—
<b>Thermal Resistance, Four-Layer Board</b>	
Junction to Ambient (θ <sub>JA</sub> )	36°C/W
Junction to Case (θ <sub>JC</sub> )	3°C/W

### 20 WLP

Package Code	W201P2+1
Outline Number	<a href="#">21-100648</a>
Land Pattern Number	<a href="#">Refer to Application Note 1891</a>
<b>Thermal Resistance, Single-Layer Board</b>	
Junction to Ambient (θ <sub>JA</sub> )	—
Junction to Case (θ <sub>JC</sub> )	—
<b>Thermal Resistance, Four-Layer Board</b>	
Junction to Ambient (θ <sub>JA</sub> )	55.49°C/W
Junction to Case (θ <sub>JC</sub> )	—

## Electrical Characteristics

(Limits are 100% tested at  $T_A = +25^\circ\text{C}$  and  $T_A = +105^\circ\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
<b>POWER / BOTH SINGLE-SUPPLY OPERATION AND DUAL-SUPPLY OPERATION</b>							
Supply Voltage	$V_{DDIO}$	$V_{DDIO}$ must be connected to $V_{DDA}$		1.71	1.8	3.63	V
Supply Voltage, Core	$V_{CORE}$	Dual-supply operation	PWRSEQ_LPCTR L.ovr = 0b00	0.855	0.9	0.945	V
			PWRSEQ_LPCTR L.ovr = 0b01	0.95	1.0	1.05	
			Default PWRSEQ_LPCTR L.ovr = 0b10	1.045	1.1	1.155	
		No power supply connection for single-supply operation				—	
Supply Voltage, Analog	$V_{DDA}$	$V_{DDA}$ must be connected to $V_{DDIO}$		1.71	1.8	3.63	V
Power-Fail Reset Voltage	$V_{RST}$	Monitors $V_{DDIO}$		1.58		1.71	V
		Monitors $V_{CORE}$ during dual-supply operation		0.74		0.845	
Power-On Reset Voltage	$V_{POR}$	Monitors $V_{DDIO}$			1.4		V
		Monitors $V_{CORE}$ during dual-supply operation			0.6		
<b>POWER / SINGLE-SUPPLY OPERATION (<math>V_{DDIO}</math> ONLY); <math>f_{SYS\_OSC} = IPO</math></b>							
$V_{DDIO}$ Current, ACTIVE Mode	$I_{DDIO\_DACTS}$	Dynamic, IPO enabled, total current into $V_{DDIO}$ pin, $V_{DDIO} = 3.3\text{V}$ , CPU in ACTIVE mode executing CoreMark; inputs tied to $V_{SS}$ or $V_{DDIO}$ ; outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V, $f_{SYS\_CLK(MAX)} = 100\text{MHz}$		54		$\mu\text{A/MHz}$
			PWRSEQ_LPCTR L.ovr = 0b01, internal regulator set to 1.0V, $f_{SYS\_CLK(MAX)} = 50\text{MHz}$		52		
			PWRSEQ_LPCTR L.ovr = 0b00, internal regulator set to 0.9V, $f_{SYS\_CLK(MAX)} = 12\text{MHz}$		50		
		Dynamic, IPO enabled, total current into $V_{DDIO}$ pin, $V_{DDIO} = 1.8\text{V}$ , CPU in ACTIVE mode executing CoreMark; inputs tied to $V_{SS}$ or	PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V, $f_{SYS\_CLK(MAX)} = 100\text{MHz}$		53		
			PWRSEQ_LPCTR L.ovr = 0b01, internal regulator set to 1.0V,		51		



(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
		V <sub>DDIO</sub> ; outputs source/sink 0mA	f <sub>SYS_CLK(MAX)</sub> = 50MHz				
			PWRSEQ_LPCTR L.ovr = 0b00, internal regulator set to 0.9V, f <sub>SYS_CLK(MAX)</sub> = 12MHz		49		
			PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V, f <sub>SYS_CLK(MAX)</sub> = 100MHz		44		
		Dynamic, IPO enabled, total current into V <sub>DDIO</sub> pin, V <sub>DDIO</sub> = 3.3V, CPU in ACTIVE mode executing While(1); inputs tied to V <sub>SS</sub> or V <sub>DDIO</sub> ; outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b01, internal regulator set to 1.0V, f <sub>SYS_CLK(MAX)</sub> = 50MHz		42		
	I <sub>DD_DACTS</sub>	Dynamic, IPO enabled, total current into V <sub>DDIO</sub> pin, V <sub>DDIO</sub> = 3.3V, CPU in ACTIVE mode executing While(1); inputs tied to V <sub>SS</sub> or V <sub>DDIO</sub> ; outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b00, internal regulator set to 0.9V, f <sub>SYS_CLK(MAX)</sub> = 12MHz		40		
			PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V, f <sub>SYS_CLK(MAX)</sub> = 100MHz		43		
			PWRSEQ_LPCTR L.ovr = 0b01, internal regulator set to 1.0V, f <sub>SYS_CLK(MAX)</sub> = 50MHz		41		
			PWRSEQ_LPCTR L.ovr = 0b00, internal regulator set to 0.9V, f <sub>SYS_CLK(MAX)</sub> = 12MHz		39		
	I <sub>DD_FACTS</sub>	Fixed, IPO enabled, total current into V <sub>DDIO</sub>	PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V. See		685		μA

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
		and $V_{DDA}$ pins, $V_{DDIO} = 3.3\text{V}$ , CPU in ACTIVE mode 0MHz execution, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	<a href="#">Table 8</a> for temperature variance.			
		PWRSEQ_LPCTR L.ovr = 0b01, internal regulator set to 1.0V. See <a href="#">Table 8</a> for temperature variance.		585		
		PWRSEQ_LPCTR L.ovr = 0b00, internal regulator set to 0.9V. See <a href="#">Table 8</a> for temperature variance.			510	
		PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V. See <a href="#">Table 8</a> for temperature variance.			665	
		PWRSEQ_LPCTR L.ovr = 0b01, internal regulator set to 1.0V. See <a href="#">Table 8</a> for temperature variance.			565	
		PWRSEQ_LPCTR L.ovr = 0b00, internal regulator set to 0.9V. See <a href="#">Table 8</a> for temperature variance.			490	
	$I_{DD\_DSLPS}$	Dynamic, IPO enabled, total current into $V_{DDIO}$ and $V_{DDA}$ pins, $V_{DDIO} = 1.8\text{V}$ , CPU in ACTIVE mode 0MHz execution, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA				
		Dynamic, IPO enabled, total current into $V_{DDIO}$ pin, $V_{DDIO} = 3.3\text{V}$ , CPU in SLEEP mode, standard DMA with 2 channels active, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V, $f_{\text{SYS\_CLK}(\text{MAX})} = 100\text{MHz}$		27	
$V_{DDIO}$ Current, SLEEP Mode	$I_{DDIO\_DSLPS}$	Dynamic, IPO enabled, total	PWRSEQ_LPCTR L.ovr = 0b01, internal regulator		26	$\mu\text{A}/\text{MHz}$

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
		current into $V_{DDIO}$ pin, $V_{DDIO} = 3.3\text{V}$ , CPU in SLEEP mode, standard DMA with 2 channels active, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA				
				26		
		Dynamic, IPO enabled, total current into $V_{DDIO}$ pin, $V_{DDIO} = 1.8\text{V}$ , CPU in SLEEP mode, standard DMA with 2 channels active, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA		27		
				26		
				26		
		Dynamic, IPO enabled, total current into $V_{DDIO}$ pin, $V_{DDIO} = 3.3\text{V}$ , CPU in SLEEP mode, DMA disabled, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA		12		
				11		
				11		
		Dynamic, IPO enabled, total current into $V_{DDIO}$ pin, $V_{DDIO} = 1.8\text{V}$ , CPU in SLEEP mode, DMA disabled, inputs		12		

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
		<p>Dynamic, IPO enabled, total current into <math>V_{DDIO}</math> pin, <math>V_{DDIO} = 1.8\text{V}</math>, CPU in SLEEP mode, inputs tied to <math>V_{SS}</math> or <math>V_{DDIO}</math>, outputs source/sink 0mA</p>	<p>PWRSEQ_LPCTR L.ovr = 0b01, internal regulator set to 1.0V, <math>f_{\text{SYS\_CLK(MAX)}} = 50\text{MHz}</math></p>		11		
		<p>Dynamic, IPO enabled, total current into <math>V_{DDIO}</math> pin, <math>V_{DDIO} = 1.8\text{V}</math>, CPU in SLEEP mode, DMA disabled, inputs tied to <math>V_{SS}</math> or <math>V_{DDIO}</math>, outputs source/sink 0mA</p>	<p>PWRSEQ_LPCTR L.ovr = 0b00, internal regulator set to 0.9V, <math>f_{\text{SYS\_CLK(MAX)}} = 12\text{MHz}</math></p>		11		
	I <sub>DDIO_FSLPS</sub>	<p>Fixed, IPO enabled, total current into <math>V_{DDIO}</math> and <math>V_{DDA}</math> pins, <math>V_{DDIO} = 3.3\text{V}</math>, CPU in SLEEP mode, inputs tied to <math>V_{SS}</math> or <math>V_{DDIO}</math>, outputs source/sink 0mA</p>	<p>PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V. See <a href="#">Table 9</a> for temperature variance.</p>		685		μA
<p>PWRSEQ_LPCTR L.ovr = 0b01, internal regulator set to 1.0V. See <a href="#">Table 9</a> for temperature variance.</p>				585			
<p>PWRSEQ_LPCTR L.ovr = 0b00, internal regulator set to 0.9V. See <a href="#">Table 9</a> for temperature variance.</p>				510			
<p>PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V. See <a href="#">Table 9</a> for temperature variance.</p>				665			
		<p>Fixed, IPO enabled, total current into <math>V_{DDIO}</math> and <math>V_{DDA}</math> pins, <math>V_{DDIO} = 1.8\text{V}</math>, CPU in SLEEP mode, inputs tied to <math>V_{SS}</math> or <math>V_{DDIO}</math>, outputs source/sink 0mA</p>	<p>PWRSEQ_LPCTR L.ovr = 0b01,</p>		565		

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
			internal regulator set to 1.0V. See <a href="#">Table 9</a> for temperature variance.				
		Fixed, IPO enabled, total current into $V_{DDIO}$ pin, $V_{DDIO} = 1.8\text{V}$ , CPU in SLEEP mode, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b00, internal regulator set to 0.9V. See <a href="#">Table 9</a> for temperature variance.		490		
SLEEP Mode Resume Time	$t_{SLP\_ONS}$	$f_{SYS\_OSC} = \text{IPO}$ , time from power mode exit to execution of application code			1.5		$\mu\text{s}$
DEEPSLEEP Mode Resume Time	$t_{DSL\_ONS}$	$f_{SYS\_OSC} = \text{IPO}$ , time from power mode exit to execution of application code	fastwk_en = 1		75		$\mu\text{s}$
			fastwk_en = 0		210		
BACKUP Mode Resume Time	$t_{BKU\_ONS}$	$f_{SYS\_OSC} = \text{IPO}$ , time from power mode exit to execution of application code	fastwk_en = 1		910		ms
			fastwk_en = 0		1020		
STORAGE Mode Resume Time	$t_{STO\_ONS}$	$f_{SYS\_OSC} = \text{IPO}$ , time from power mode exit to execution of application code	fastwk_en = 1		920		ms
			fastwk_en = 0		1030		
<b>POWER / SINGLE-SUPPLY OPERATION (<math>V_{DDIO}</math> ONLY); <math>f_{SYS\_OSC} = \text{IBRO}</math></b>							
$V_{DDIO}$ Current, ACTIVE Mode	$I_{DDIO\_DACTS}$	Dynamic, IBRO enabled, total current into $V_{DDIO}$ pin, $V_{DDIO} = 3.3\text{V}$ , CPU in ACTIVE mode, executing CoreMark, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V, $f_{SYS\_CLK(\text{MAX})} = 7.3728\text{MHz}$		55		$\mu\text{A/MHz}$
			PWRSEQ_LPCTR L.ovr = 0b01, internal regulator set to 1.0V, $f_{SYS\_CLK(\text{MAX})} = 7.3728\text{MHz}$		52		
			PWRSEQ_LPCTR L.ovr = 0b00, internal regulator set to 0.9V, $f_{SYS\_CLK(\text{MAX})} = 7.3728\text{MHz}$		49		

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
		Dynamic, IBRO enabled, total current into $V_{DDIO}$ pin, $V_{DDIO} = 1.8\text{V}$ , CPU in ACTIVE mode, executing CoreMark, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V, $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$		54	
			PWRSEQ_LPCTR L.ovr = 0b01, internal regulator set to 1.0V, $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$		51	
			PWRSEQ_LPCTR L.ovr = 0b00, internal regulator set to 0.9V, $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$		48	
		Dynamic, IBRO enabled, total current into $V_{DDIO}$ pin, $V_{DDIO} = 3.3\text{V}$ , CPU in ACTIVE mode, executing While(1), inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V, $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$		44	
			PWRSEQ_LPCTR L.ovr = 0b01, internal regulator set to 1.0V, $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$		41	
			PWRSEQ_LPCTR L.ovr = 0b00, internal regulator set to 0.9V, $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$		39	
		Dynamic, IBRO enabled, total current into $V_{DDIO}$ pin, $V_{DDIO} = 1.8\text{V}$ , CPU in ACTIVE mode, executing While(1), inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V, $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$		43	
			PWRSEQ_LPCTR L.ovr = 0b01, internal regulator set to 1.0V, $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$		41	
			PWRSEQ_LPCTR L.ovr = 0b00, internal regulator set to 0.9V,		38	

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
	I <sub>DDIO_FACTS</sub>	Fixed, IBRO enabled, total current into V <sub>DDIO</sub> and V <sub>DDA</sub> pins, V <sub>DDIO</sub> = 3.3V, CPU in ACTIVE mode 0MHz execution, inputs tied to V <sub>SS</sub> or V <sub>DDIO</sub> , outputs source/sink 0mA	f <sub>SYS_CLK(MAX)</sub> = 7.3728MHz				μA
			PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V. See <a href="#">Table 10</a> for temperature variance.		280		
			PWRSEQ_LPCTR L.ovr = 0b01, internal regulator set to 1.0V. See <a href="#">Table 10</a> for temperature variance.		255		
			PWRSEQ_LPCTR L.ovr = 0b00, internal regulator set to 0.9V. See <a href="#">Table 10</a> for temperature variance.		235		
			PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V. See <a href="#">Table 10</a> for temperature variance.		255		
			PWRSEQ_LPCTR L.ovr = 0b01, internal regulator set to 1.0V. See <a href="#">Table 10</a> for temperature variance.		230		
			PWRSEQ_LPCTR L.ovr = 0b00, internal regulator set to 0.9V. See <a href="#">Table 10</a> for temperature variance.		210		
			V <sub>DDIO</sub> Current, SLEEP Mode	I <sub>DDIO_DSLPS</sub>	Dynamic, IBRO enabled, total current into V <sub>DDIO</sub> pin, V <sub>DDIO</sub> = 3.3V, CPU in SLEEP mode, standard DMA with 2	PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V, f <sub>SYS_CLK(MAX)</sub> = 7.3728MHz	
PWRSEQ_LPCTR L.ovr = 0b01,		25					

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
		channels active, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	internal regulator set to 1.0V, $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$				
			PWRSEQ_LPCTR L.ovr = 0b00, internal regulator set to 0.9V, $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$		24		
		Dynamic, IBRO enabled, total current into $V_{DDIO}$ pin, $V_{DDIO} = 1.8\text{V}$ , CPU in SLEEP mode, standard DMA with 2 channels active, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V, $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$			26	
			PWRSEQ_LPCTR L.ovr = 0b01, internal regulator set to 1.0V, $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$			25	
			PWRSEQ_LPCTR L.ovr = 0b00, internal regulator set to 0.9V, $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$			23	
			PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V, $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$			11	
		Dynamic, IBRO enabled, total current into $V_{DDIO}$ pin, $V_{DDIO} = 3.3\text{V}$ , CPU in SLEEP mode, DMA disabled, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b01, internal regulator set to 1.0V, $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$			10	
			PWRSEQ_LPCTR L.ovr = 0b00, internal regulator set to 0.9V, $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$			9	
			PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V, $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$			11	
		Dynamic, IBRO enabled, total current into $V_{DDIO}$ pin, $V_{DDIO} = 1.8\text{V}$ , CPU in SLEEP	PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V, $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$			11	



(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
		mode, DMA disabled, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b01, internal regulator set to 1.0V, $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$		10		
			PWRSEQ_LPCTR L.ovr = 0b00, internal regulator set to 0.9V, $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$		9		
	IDDIO_FSLPS	Fixed, IBRO enabled, total current into $V_{DDIO}$ and $V_{DDA}$ pins, $V_{DDIO} = 3.3\text{V}$ , CPU in SLEEP mode, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V. See <a href="#">Table 11</a> for temperature variance.		280		$\mu\text{A}$
			PWRSEQ_LPCTR L.ovr = 0b01, internal regulator set to 1.0V. See <a href="#">Table 11</a> for temperature variance.		255		
			PWRSEQ_LPCTR L.ovr = 0b00, internal regulator set to 0.9V. See <a href="#">Table 11</a> for temperature variance.		235		
		Fixed, IBRO enabled, total current into $V_{DDIO}$ and $V_{DDA}$ pins, $V_{DDIO} = 1.8\text{V}$ , CPU in SLEEP mode, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, internal regulator set to 1.1V. See <a href="#">Table 11</a> for temperature variance.		255		
			PWRSEQ_LPCTR L.ovr = 0b01, internal regulator set to 1.0V. See <a href="#">Table 11</a> for temperature variance.		230		
			PWRSEQ_LPCTR L.ovr = 0b00, internal regulator set to 0.9V. See <a href="#">Table 11</a> for		210		

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
			temperature variance.				
SLEEP Mode Resume Time	$t_{\text{SLP\_ONS}}$	$f_{\text{SYS\_OSC}} = \text{IBRO}$ , time from power mode exit to execution of application code			20.5		$\mu\text{s}$
DEEPSLEEP Mode Resume Time	$t_{\text{DSL\_ONS}}$	$f_{\text{SYS\_OSC}} = \text{IBRO}$ , time from power mode exit to execution of application code	fastwk_en = 1		205		$\mu\text{s}$
			fastwk_en = 0		350		
BACKUP Mode Resume Time	$t_{\text{BKU\_ONS}}$	$f_{\text{SYS\_OSC}} = \text{IBRO}$ , time from power mode exit to execution of application code	fastwk_en = 1		11.55		ms
			fastwk_en = 0		11.67		
STORAGE Mode Resume Time	$t_{\text{STO\_ONS}}$	$f_{\text{SYS\_OSC}} = \text{IBRO}$ , time from power mode exit to execution of application code	fastwk_en = 1		11.72		ms
			fastwk_en = 0		11.74		
<b>POWER / SINGLE-SUPPLY OPERATION (<math>V_{\text{DDIO}}</math> ONLY)</b>							
$V_{\text{DDIO}}$ Fixed Current, DEEPSLEEP Mode	$I_{\text{DDIO\_FDSL S}}$	Standby state with full data retention and 80KB SRAM retained	$V_{\text{DDIO}} = 3.3\text{V}$ , PWRSEQ_LPCTR L.bg_dis = 0. See <a href="#">Table 12</a> for temperature variance.		3.6		$\mu\text{A}$
			$V_{\text{DDIO}} = 1.8\text{V}$ , PWRSEQ_LPCTR L.bg_dis = 0. See <a href="#">Table 12</a> for temperature variance.		3.3		
$V_{\text{DDIO}}$ Fixed Current, BACKUP Mode	$I_{\text{DDIO\_FBKUS}}$	$V_{\text{DDIO}} = 3.3\text{V}$ , RTC disabled	0KB SRAM retained, retention regulator disabled. See <a href="#">Table 13</a> for temperature variance.		0.45		$\mu\text{A}$
			20KB SRAM retained. See <a href="#">Table 13</a> for temperature variance.		1.25		
			40KB SRAM retained. See <a href="#">Table 13</a> for temperature variance.		1.6		
			60KB SRAM retained. See <a href="#">Table 13</a> for temperature variance.		2		

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
			80KB SRAM retained. See <a href="#">Table 13</a> for temperature variance.		2.4		
			0KB SRAM retained, retention regulator disabled. See <a href="#">Table 13</a> for temperature variance.		0.25		
		$V_{DDIO} = 1.8\text{V}$ , RTC disabled	20KB SRAM retained. See <a href="#">Table 13</a> for temperature variance.		1		
			40KB SRAM retained. See <a href="#">Table 13</a> for temperature variance.		1.4		
			60KB SRAM retained. See <a href="#">Table 13</a> for temperature variance.		1.8		
			80KB SRAM retained. See <a href="#">Table 13</a> for temperature variance.		2.15		
$V_{DDIO}$ Fixed Current, STORAGE Mode	$I_{DDIO\_FSTOS}$	$V_{DDIO} = 3.3\text{V}$ . See <a href="#">Table 14</a> for temperature variance.			0.23		$\mu\text{A}$
		$V_{DDIO} = 1.8\text{V}$ . See <a href="#">Table 14</a> for temperature variance.			0.06		
<b>POWER / DUAL-SUPPLY OPERATION (<math>V_{DDIO}</math> AND <math>V_{CORE}</math>); <math>f_{\text{SYS\_OSC}} = \text{IPO}</math></b>							
$V_{CORE}$ Current, ACTIVE mode	$I_{CORE\_DACTD}$	Dynamic, IPO enabled, total current into $V_{CORE}$ pin, CPU in ACTIVE mode, executing CoreMark, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	$\text{PWRSEQ\_LPCTR L.ovr} = 0\text{b}10$ , $V_{CORE} = 1.1\text{V}$ , $f_{\text{SYS\_CLK(MAX)}} = 100\text{MHz}$		53		$\mu\text{A/MHz}$
			$\text{PWRSEQ\_LPCTR L.ovr} = 0\text{b}01$ , $V_{CORE} = 1.0\text{V}$ , $f_{\text{SYS\_CLK(MAX)}} = 50\text{MHz}$		52		
			$\text{PWRSEQ\_LPCTR L.ovr} = 0\text{b}00$ , $V_{CORE} = 0.9\text{V}$ , $f_{\text{SYS\_CLK(MAX)}} = 12\text{MHz}$		46		
		Dynamic, IPO enabled, total current into $V_{CORE}$ pin, CPU in ACTIVE mode,	$\text{PWRSEQ\_LPCTR L.ovr} = 0\text{b}10$ , $V_{CORE} = 1.1\text{V}$ , $f_{\text{SYS\_CLK(MAX)}} = 100\text{MHz}$		43		

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
		executing While(1), inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b01, $V_{CORE} = 1.0\text{V}$ , $f_{SYS\_CLK(MAX)} = 50\text{MHz}$		41		
			PWRSEQ_LPCTR L.ovr = 0b00, $V_{CORE} = 0.9\text{V}$ , $f_{SYS\_CLK(MAX)} = 12\text{MHz}$		37		
	I <sub>CORE_FACTD</sub>	Fixed, IPO enabled, total current into $V_{CORE}$ pin, CPU in ACTIVE mode 0MHz execution, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, $V_{CORE} = 1.1\text{V}$ . See <a href="#">Table 15</a> for temperature variance.		250		$\mu\text{A}$
			PWRSEQ_LPCTR L.ovr = 0b01, $V_{CORE} = 1.0\text{V}$ . See <a href="#">Table 15</a> for temperature variance.		145		
			PWRSEQ_LPCTR L.ovr = 0b00, $V_{CORE} = 0.9\text{V}$ . See <a href="#">Table 15</a> for temperature variance.		70		
	V <sub>DDIO</sub> Current, ACTIVE mode	I <sub>DDIO_DACTD</sub>	Dynamic, IPO enabled, total current into $V_{DDIO}$ pin, $V_{DDIO} = 3.3\text{V}$ , CPU in ACTIVE mode, executing CoreMark, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, $V_{CORE} = 1.1\text{V}$ , $f_{SYS\_CLK(MAX)} = 100\text{MHz}$		2	$\mu\text{A/MHz}$
PWRSEQ_LPCTR L.ovr = 0b01, $V_{CORE} = 1.0\text{V}$ , $f_{SYS\_CLK(MAX)} = 50\text{MHz}$					2		
PWRSEQ_LPCTR L.ovr = 0b00, $V_{CORE} = 0.9\text{V}$ , $f_{SYS\_CLK(MAX)} = 12\text{MHz}$				2			
PWRSEQ_LPCTR L.ovr = 0b10, $V_{CORE} = 1.1\text{V}$ , $f_{SYS\_CLK(MAX)} = 100\text{MHz}$				2			
Dynamic, IPO enabled, total current into $V_{DDIO}$ pin, $V_{DDIO} = 1.8\text{V}$ , CPU in ACTIVE mode, executing CoreMark, inputs tied to $V_{SS}$ or		PWRSEQ_LPCTR L.ovr = 0b10, $V_{CORE} = 1.1\text{V}$ , $f_{SYS\_CLK(MAX)} = 100\text{MHz}$		2			
		PWRSEQ_LPCTR L.ovr = 0b01, $V_{CORE} = 1.0\text{V}$ ,		2			

(Limits are 100% tested at  $T_A = +25^\circ\text{C}$  and  $T_A = +105^\circ\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS		
		V <sub>DDIO</sub> , outputs source/sink 0mA	f <sub>SYS_CLK(MAX)</sub> = 50MHz					
			PWRSEQ_LPCTR L.ovr = 0b00, V <sub>CORE</sub> = 0.9V, f <sub>SYS_CLK(MAX)</sub> = 12MHz		2			
		Dynamic, IPO enabled, total current into V <sub>DDIO</sub> pin, V <sub>DDIO</sub> = 3.3V, CPU in ACTIVE mode, executing While(1), inputs tied to V <sub>SS</sub> or V <sub>DDIO</sub> , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, V <sub>CORE</sub> = 1.1V, f <sub>SYS_CLK(MAX)</sub> = 100MHz		2			
			PWRSEQ_LPCTR L.ovr = 0b01, V <sub>CORE</sub> = 1.0V, f <sub>SYS_CLK(MAX)</sub> = 50MHz		2			
			PWRSEQ_LPCTR L.ovr = 0b00, V <sub>CORE</sub> = 0.9V, f <sub>SYS_CLK(MAX)</sub> = 12MHz		2			
		Dynamic, IPO enabled, total current into V <sub>DDIO</sub> pin, V <sub>DDIO</sub> = 1.8V, CPU in ACTIVE mode, executing While(1), inputs tied to V <sub>SS</sub> or V <sub>DDIO</sub> , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, V <sub>CORE</sub> = 1.1V, f <sub>SYS_CLK(MAX)</sub> = 100MHz		2			
			PWRSEQ_LPCTR L.ovr = 0b01, V <sub>CORE</sub> = 1.0V, f <sub>SYS_CLK(MAX)</sub> = 50MHz		2			
			PWRSEQ_LPCTR L.ovr = 0b00, V <sub>CORE</sub> = 0.9V, f <sub>SYS_CLK(MAX)</sub> = 12MHz		2			
		I <sub>DDIO_FACTD</sub>	Fixed, IPO enabled, total current into V <sub>DDIO</sub> pin, V <sub>DDIO</sub> = 3.3V, CPU in ACTIVE mode 0MHz execution, inputs tied to V <sub>SS</sub> or V <sub>DDIO</sub> , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 16</a> for temperature variance.		385		μA
				PWRSEQ_LPCTR L.ovr = 0b01, V <sub>CORE</sub> = 1.0V. See <a href="#">Table 16</a> for temperature variance.		385		
				PWRSEQ_LPCTR L.ovr = 0b00,		385		

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
		$V_{\text{CORE}} = 0.9\text{V}$ . See <a href="#">Table 16</a> for temperature variance.					
		Fixed, IPO enabled, total current into $V_{\text{DDIO}}$ pin, $V_{\text{DDIO}} = 1.8\text{V}$ , CPU in ACTIVE mode 0MHz execution, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA PWRSEQ_LPCTR L.ovr = 0b10, $V_{\text{CORE}} = 1.1\text{V}$ . See <a href="#">Table 16</a> for temperature variance.		370			
		PWRSEQ_LPCTR L.ovr = 0b01, $V_{\text{CORE}} = 1.0\text{V}$ . See <a href="#">Table 16</a> for temperature variance.		370			
		PWRSEQ_LPCTR L.ovr = 0b00, $V_{\text{CORE}} = 0.9\text{V}$ . See <a href="#">Table 16</a> for temperature variance.		370			
		Dynamic, IPO enabled, total current into $V_{\text{CORE}}$ pin, CPU in SLEEP mode, standard DMA with 2 channels active, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, $V_{\text{CORE}} = 1.1\text{V}$ , $f_{\text{SYS\_CLK(MAX)}} = 100\text{MHz}$		28		
			PWRSEQ_LPCTR L.ovr = 0b01, $V_{\text{CORE}} = 1.0\text{V}$ , $f_{\text{SYS\_CLK(MAX)}} = 50\text{MHz}$		26		
PWRSEQ_LPCTR L.ovr = 0b00, $V_{\text{CORE}} = 0.9\text{V}$ , $f_{\text{SYS\_CLK(MAX)}} = 12\text{MHz}$			24				
$V_{\text{CORE}}$ Current, SLEEP Mode	$I_{\text{CORE\_DSLDP}}$	Dynamic, IPO enabled, total current into $V_{\text{CORE}}$ pin, CPU in SLEEP mode, DMA disabled, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, $V_{\text{CORE}} = 1.1\text{V}$ , $f_{\text{SYS\_CLK(MAX)}} = 100\text{MHz}$		12		
			PWRSEQ_LPCTR L.ovr = 0b01, $V_{\text{CORE}} = 1.0\text{V}$ , $f_{\text{SYS\_CLK(MAX)}} = 50\text{MHz}$		11		
			PWRSEQ_LPCTR L.ovr = 0b00, $V_{\text{CORE}} = 0.9\text{V}$		10		
						$\mu\text{A/MHz}$	

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
	$I_{\text{CORE\_FSLPD}}$	Fixed, IPO enabled, total current into $V_{\text{CORE}}$ pin, CPU in SLEEP mode, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	$f_{\text{SYS\_CLK(MAX)}} = 12\text{MHz}$				
			PWRSEQ_LPCTR L.ovr = 0b10, $V_{\text{CORE}} = 1.1\text{V}$ . See <a href="#">Table 17</a> for temperature variance.		250		
			PWRSEQ_LPCTR L.ovr = 0b01, $V_{\text{CORE}} = 1.0\text{V}$ . See <a href="#">Table 17</a> for temperature variance.		145		
						$\mu\text{A}$	
$V_{\text{DDIO}}$ Current, SLEEP Mode	$I_{\text{DDIO\_DSLDP}}$	Dynamic, IPO enabled, total current into $V_{\text{DDIO}}$ pin, $V_{\text{DDIO}} = 3.3\text{V}$ , CPU in SLEEP mode, standard DMA with 2 channels active, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, $V_{\text{CORE}} = 1.1\text{V}$ , $f_{\text{SYS\_CLK(MAX)}} = 100\text{MHz}$		2		
			PWRSEQ_LPCTR L.ovr = 0b01, $V_{\text{CORE}} = 1.0\text{V}$ , $f_{\text{SYS\_CLK(MAX)}} = 50\text{MHz}$		2		
			PWRSEQ_LPCTR L.ovr = 0b00, $V_{\text{CORE}} = 0.9\text{V}$ , $f_{\text{SYS\_CLK(MAX)}} = 12\text{MHz}$		2		
		Dynamic, IPO enabled, total current into $V_{\text{DDIO}}$ pin, $V_{\text{DDIO}} = 1.8\text{V}$ , CPU in SLEEP mode, standard DMA with 2 channels active, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, $V_{\text{CORE}} = 1.1\text{V}$ , $f_{\text{SYS\_CLK(MAX)}} = 100\text{MHz}$		2		
			PWRSEQ_LPCTR L.ovr = 0b01, $V_{\text{CORE}} = 1.0\text{V}$ , $f_{\text{SYS\_CLK(MAX)}} = 50\text{MHz}$		2		
			PWRSEQ_LPCTR L.ovr = 0b00, $V_{\text{CORE}} = 0.9\text{V}$ , $f_{\text{SYS\_CLK(MAX)}} = 12\text{MHz}$		2		
						$\mu\text{A/MHz}$	

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS		
	IDDIO_FSLPD	Fixed, IPO enabled, total current into VDDIO pin, VDDIO = 3.3V, CPU in SLEEP mode, inputs tied to VSS or VDDIO, outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, VCORE = 1.1V. See <a href="#">Table 18</a> for temperature variance.		385		$\mu\text{A}$		
			PWRSEQ_LPCTR L.ovr = 0b01, VCORE = 1.0V. See <a href="#">Table 18</a> for temperature variance.		385				
			PWRSEQ_LPCTR L.ovr = 0b00, VCORE = 0.9V. See <a href="#">Table 18</a> for temperature variance.		385				
		Fixed, IPO enabled, total current into VDDIO pin, VDDIO = 1.8V, CPU in SLEEP mode, inputs tied to VSS or VDDIO, outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, VCORE = 1.1V. See <a href="#">Table 18</a> for temperature variance.		370				
			PWRSEQ_LPCTR L.ovr = 0b01, VCORE = 1.0V. See <a href="#">Table 18</a> for temperature variance.		370				
			PWRSEQ_LPCTR L.ovr = 0b00, VCORE = 0.9V. See <a href="#">Table 18</a> for temperature variance.		370				
		SLEEP Mode Resume Time	tSLP_OND	fSYS_OSC = IPO, time from power mode exit to execution of application code		1.5			$\mu\text{s}$
		DEEPSLEEP Mode Resume Time	tDSL_OND	fSYS_OSC = IPO, time from power mode exit to execution of application code	fastwk_en = 1			75	$\mu\text{s}$
fastwk_en = 0					210				
BACKUP Mode Resume Time	tBKU_OND	fSYS_OSC = IPO, time from power mode exit to execution of application code	fastwk_en = 1		910	ms			
			fastwk_en = 0		1020				
STORAGE Mode Resume Time	tSTO_OND	fSYS_OSC = IPO, time from power mode exit to	fastwk_en = 1		920	ms			
			fastwk_en = 0		1030				



(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
		execution of application code					
<b>POWER / DUAL-SUPPLY OPERATION (<math>V_{DDIO}</math> AND <math>V_{CORE}</math>); <math>f_{SYS\_OSC} = IBRO</math></b>							
$V_{CORE}$ Current, ACTIVE mode	$I_{CORE\_DACTD}$	Dynamic, IBRO enabled, total current into $V_{CORE}$ pin, CPU in ACTIVE mode, executing CoreMark, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, $V_{CORE} = 1.1\text{V}$ , $f_{SYS\_CLK(MAX)} = 7.3728\text{MHz}$		54		$\mu\text{A/MHz}$
			PWRSEQ_LPCTR L.ovr = 0b01, $V_{CORE} = 1.0\text{V}$ , $f_{SYS\_CLK(MAX)} = 7.3728\text{MHz}$		50		
			PWRSEQ_LPCTR L.ovr = 0b00, $V_{CORE} = 0.9\text{V}$ , $f_{SYS\_CLK(MAX)} = 7.3728\text{MHz}$		41		
		Dynamic, IBRO enabled, total current into $V_{CORE}$ pin, CPU in ACTIVE mode, executing While(1), inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, $V_{CORE} = 1.1\text{V}$ , $f_{SYS\_CLK(MAX)} = 7.3728\text{MHz}$		44		
			PWRSEQ_LPCTR L.ovr = 0b01, $V_{CORE} = 1.0\text{V}$ , $f_{SYS\_CLK(MAX)} = 7.3728\text{MHz}$		40		
			PWRSEQ_LPCTR L.ovr = 0b00, $V_{CORE} = 0.9\text{V}$ , $f_{SYS\_CLK(MAX)} = 7.3728\text{MHz}$		34		
	$I_{CORE\_FACTD}$	Fixed, IBRO enabled, total current into $V_{CORE}$ pin, CPU in ACTIVE mode 0MHz execution, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, $V_{CORE} = 1.1\text{V}$ . See <a href="#">Table 19</a> for temperature variance.		105		$\mu\text{A}$
			PWRSEQ_LPCTR L.ovr = 0b01, $V_{CORE} = 1.0\text{V}$ . See <a href="#">Table 19</a> for temperature variance.		80		
			PWRSEQ_LPCTR L.ovr = 0b00, $V_{CORE} = 0.9\text{V}$ . See <a href="#">Table 19</a> for temperature variance.		55		

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS	
V <sub>DDIO</sub> Current, ACTIVE Mode	I <sub>DDIO_DACTD</sub>	Dynamic, IBRO enabled, total current into V <sub>DDIO</sub> pin, V <sub>DDIO</sub> = 3.3V, CPU in ACTIVE mode, executing CoreMark, inputs tied to V <sub>SS</sub> or V <sub>DDIO</sub> , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, f <sub>SYS_CLK</sub> (MAX) = 7.3728MHz		2		μA/MHz	
			PWRSEQ_LPCTR L.ovr = 0b01, f <sub>SYS_CLK</sub> (MAX) = 7.3728MHz		2			
			PWRSEQ_LPCTR L.ovr = 0b00, f <sub>SYS_CLK</sub> (MAX) = 7.3728MHz		2			
		Dynamic, IBRO enabled, total current into V <sub>DDIO</sub> pin, V <sub>DDIO</sub> = 1.8V, CPU in ACTIVE mode, executing CoreMark, inputs tied to V <sub>SS</sub> or V <sub>DDIO</sub> , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, f <sub>SYS_CLK</sub> (MAX) = 7.3728MHz		2			
			PWRSEQ_LPCTR L.ovr = 0b01, f <sub>SYS_CLK</sub> (MAX) = 7.3728MHz		2			
			PWRSEQ_LPCTR L.ovr = 0b00, f <sub>SYS_CLK</sub> (MAX) = 7.3728MHz		2			
		Dynamic, IBRO enabled, total current into V <sub>DDIO</sub> pin, V <sub>DDIO</sub> = 3.3V, CPU in ACTIVE mode, executing While(1), inputs tied to V <sub>SS</sub> or V <sub>DDIO</sub> , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, f <sub>SYS_CLK</sub> (MAX) = 7.3728MHz		2			
			PWRSEQ_LPCTR L.ovr = 0b01, f <sub>SYS_CLK</sub> (MAX) = 7.3728MHz		2			
			PWRSEQ_LPCTR L.ovr = 0b00, f <sub>SYS_CLK</sub> (MAX) = 7.3728MHz		2			
		Dynamic, IBRO enabled, total current into V <sub>DDIO</sub> pin, V <sub>DDIO</sub> = 1.8V, CPU in ACTIVE mode, executing While(1), inputs tied to V <sub>SS</sub> or V <sub>DDIO</sub> , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, f <sub>SYS_CLK</sub> (MAX) = 7.3728MHz		2			
			PWRSEQ_LPCTR L.ovr = 0b01, f <sub>SYS_CLK</sub> (MAX) = 7.3728MHz		2			
			PWRSEQ_LPCTR L.ovr = 0b00, f <sub>SYS_CLK</sub> (MAX) = 7.3728MHz		2			
	I <sub>DDIO_FACTD</sub>	Fixed, IBRO enabled, total current into V <sub>DDIO</sub>	PWRSEQ_LPCTR L.ovr = 0b10, V <sub>CORE</sub> = 1.1V. See		115			μA

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
		pin, $V_{DDIO} = 3.3\text{V}$ , CPU in ACTIVE mode 0MHz execution, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	<a href="#">Table 20</a> for temperature variance.				
		PWRSEQ_LPCTR L.ovr = 0b01, $V_{CORE} = 1.0\text{V}$ . See <a href="#">Table 20</a> for temperature variance.		115			
		PWRSEQ_LPCTR L.ovr = 0b00, $V_{CORE} = 0.9\text{V}$ . See <a href="#">Table 20</a> for temperature variance.			115		
		Fixed, IBRO enabled, total current into $V_{DDIO}$ pin, $V_{DDIO} = 1.8\text{V}$ , CPU in ACTIVE mode 0MHz execution, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, $V_{CORE} = 1.1\text{V}$ . See <a href="#">Table 20</a> for temperature variance.			90	
		PWRSEQ_LPCTR L.ovr = 0b01, $V_{CORE} = 1.0\text{V}$ . See <a href="#">Table 20</a> for temperature variance.				90	
		PWRSEQ_LPCTR L.ovr = 0b00, $V_{CORE} = 0.9\text{V}$ . See <a href="#">Table 20</a> for temperature variance.				90	
$V_{CORE}$ Current, SLEEP Mode	$I_{CORE\_DSLDP}$	Dynamic, IBRO enabled, total current into $V_{CORE}$ pin, CPU in SLEEP mode, standard DMA with 2 channels active, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, $V_{CORE} = 1.1\text{V}$ , $f_{SYS\_CLK(MAX)} = 7.3728\text{MHz}$		27	$\mu\text{A/MHz}$	
			PWRSEQ_LPCTR L.ovr = 0b01, $V_{CORE} = 1.0\text{V}$ , $f_{SYS\_CLK(MAX)} = 7.3728\text{MHz}$		25		
			PWRSEQ_LPCTR L.ovr = 0b00, $V_{CORE} = 0.9\text{V}$ , $f_{SYS\_CLK(MAX)} = 7.3728\text{MHz}$		21		
		Dynamic, IBRO enabled, total current into $V_{CORE}$	PWRSEQ_LPCTR L.ovr = 0b10, $V_{CORE} = 1.1\text{V}$ ,		12		

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
		pin, CPU in SLEEP mode, DMA disabled, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	$f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$				
			PWRSEQ_LPCTR L.ovr = 0b01, $V_{\text{CORE}} = 1.0\text{V}$ , $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$		11		
			PWRSEQ_LPCTR L.ovr = 0b00, $V_{\text{CORE}} = 0.9\text{V}$ , $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$		10		
	$I_{\text{CORE\_FSLPD}}$	Fixed, IBRO enabled, total current into $V_{\text{CORE}}$ pin, CPU in SLEEP mode, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, $V_{\text{CORE}} = 1.1\text{V}$ . See <a href="#">Table 21</a> for temperature variance.		250		$\mu\text{A}$
			PWRSEQ_LPCTR L.ovr = 0b01, $V_{\text{CORE}} = 1.0\text{V}$ . See <a href="#">Table 21</a> for temperature variance.		145		
			PWRSEQ_LPCTR L.ovr = 0b00, $V_{\text{CORE}} = 0.9\text{V}$ . See <a href="#">Table 21</a> for temperature variance.		70		
$V_{\text{DDIO}}$ Current, SLEEP Mode	$I_{\text{DDIO\_DSLDPD}}$	Dynamic, IBRO enabled, total current into $V_{\text{DDIO}}$ pin, $V_{\text{DDIO}} = 3.3\text{V}$ , CPU in SLEEP mode, standard DMA with 2 channels active, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, $V_{\text{CORE}} = 1.1\text{V}$ , $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$		37.0	$\mu\text{A/MHz}$	
			PWRSEQ_LPCTR L.ovr = 0b01, $V_{\text{CORE}} = 1.0\text{V}$ , $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$		38		
			PWRSEQ_LPCTR L.ovr = 0b00, $V_{\text{CORE}} = 0.9\text{V}$ , $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$		37		
			PWRSEQ_LPCTR L.ovr = 0b10, $V_{\text{CORE}} = 1.1\text{V}$ , $f_{\text{SYS\_CLK(MAX)}} = 7.3728\text{MHz}$		39		

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS	
		mode, standard DMA with 2 channels active, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b01, $V_{CORE} = 1.0\text{V}$ , $f_{SYS\_CLK(MAX)} = 7.3728\text{MHz}$		39		$\mu\text{A}$	
			PWRSEQ_LPCTR L.ovr = 0b00, $V_{CORE} = 0.9\text{V}$ , $f_{SYS\_CLK(MAX)} = 7.3728\text{MHz}$		38			
	IDDIO_FSLPD	Fixed, IBRO enabled, total current into $V_{DDIO}$ pin, $V_{DDIO} = 3.3\text{V}$ , CPU in SLEEP mode, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, $V_{CORE} = 1.1\text{V}$ . See <a href="#">Table 22</a> for temperature variance.		115			
			PWRSEQ_LPCTR L.ovr = 0b01, $V_{CORE} = 1.0\text{V}$ . See <a href="#">Table 22</a> for temperature variance.		115			
			PWRSEQ_LPCTR L.ovr = 0b00, $V_{CORE} = 0.9\text{V}$ . See <a href="#">Table 22</a> for temperature variance.		115			
			PWRSEQ_LPCTR L.ovr = 0b10, $V_{CORE} = 1.1\text{V}$ . See <a href="#">Table 22</a> for temperature variance.		90			
		Fixed, IBRO enabled, total current into $V_{DDIO}$ pin, $V_{DDIO} = 1.8\text{V}$ , CPU in SLEEP mode, inputs tied to $V_{SS}$ or $V_{DDIO}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b01, $V_{CORE} = 1.0\text{V}$ . See <a href="#">Table 22</a> for temperature variance.		90			
			PWRSEQ_LPCTR L.ovr = 0b00, $V_{CORE} = 0.9\text{V}$ . See <a href="#">Table 22</a> for temperature variance.		90			
			PWRSEQ_LPCTR L.ovr = 0b01, $V_{CORE} = 1.0\text{V}$ . See <a href="#">Table 22</a> for temperature variance.		90			
	SLEEP Mode Resume Time	$t_{SLP\_OND}$	$f_{SYS\_OSC} = \text{IBRO}$ , time from power mode exit to execution of application code		20.5			$\mu\text{s}$
DEEPSLEEP Mode Resume Time	$t_{DSL\_OND}$	$f_{SYS\_OSC} = \text{IBRO}$ , time from power mode exit to	fastwk_en = 1		205	$\mu\text{s}$		
			fastwk_en = 0		350			

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS	
		execution of application code						
BACKUP Mode Resume Time	$t_{\text{BKU\_OND}}$	$f_{\text{SYS\_OSC}} = \text{IBRO}$ , time from power mode exit to execution of application code	$\text{fastwk\_en} = 1$		11.55		ms	
			$\text{fastwk\_en} = 0$		11.67			
STORAGE Mode Resume Time	$t_{\text{STO\_OND}}$	$f_{\text{SYS\_OSC}} = \text{IBRO}$ , time from power mode exit to execution of application code	$\text{fastwk\_en} = 1$		11.72		ms	
			$\text{fastwk\_en} = 0$		11.74			
<b>POWER / DUAL-SUPPLY OPERATION (<math>V_{\text{DDIO}}</math> AND <math>V_{\text{CORE}}</math>)</b>								
$V_{\text{CORE}}$ Fixed Current, DEEPSLEEP Mode	$I_{\text{CORE\_FDSL P D}}$	$V_{\text{DDIO}} = 3.3\text{V}$ , $V_{\text{CORE}} = 1.1\text{V}$	$\text{PWRSEQ\_LPCTR}$ $L.\text{bg\_dis} = 0$ . See <a href="#">Table 23</a> for temperature variance.		6.8		$\mu\text{A}$	
			$V_{\text{DDIO}} = 3.3\text{V}$ , $V_{\text{CORE}} = 0.855\text{V}$	$\text{PWRSEQ\_LPCTR}$ $L.\text{bg\_dis} = 0$ . See <a href="#">Table 23</a> for temperature variance.		2.7		
			$V_{\text{DDIO}} = 1.8\text{V}$ , $V_{\text{CORE}} = 1.1\text{V}$ .	$\text{PWRSEQ\_LPCTR}$ $L.\text{bg\_dis} = 0$ . See <a href="#">Table 23</a> for temperature variance.		6.8		
			$V_{\text{DDIO}} = 1.8\text{V}$ , $V_{\text{CORE}} = 0.855\text{V}$	$\text{PWRSEQ\_LPCTR}$ $L.\text{bg\_dis} = 0$ . See <a href="#">Table 23</a> for temperature variance.		2.7		
$V_{\text{DDIO}}$ Fixed Current, DEEPSLEEP Mode	$I_{\text{DDIO\_FDSL P D}}$	$V_{\text{DDIO}} = 3.3\text{V}$ , $V_{\text{CORE}} = 1.1\text{V}$	$\text{PWRSEQ\_LPCTR}$ $L.\text{bg\_dis} = 0$ . See <a href="#">Table 24</a> for temperature variance.		0.19		$\mu\text{A}$	
			$V_{\text{DDIO}} = 3.3\text{V}$ , $V_{\text{CORE}} = 0.855\text{V}$	$\text{PWRSEQ\_LPCTR}$ $L.\text{bg\_dis} = 0$ . See <a href="#">Table 24</a> for temperature variance.		0.19		
			$V_{\text{DDIO}} = 1.8\text{V}$ , $V_{\text{CORE}} = 1.1\text{V}$	$\text{PWRSEQ\_LPCTR}$ $L.\text{bg\_dis} = 0$ . See <a href="#">Table 24</a> for temperature variance.		0.05		
			$V_{\text{DDIO}} = 1.8\text{V}$ , $V_{\text{CORE}} = 0.855\text{V}$	$\text{PWRSEQ\_LPCTR}$ $L.\text{bg\_dis} = 0$ . See <a href="#">Table 24</a> for		0.05		

(Limits are 100% tested at  $T_A = +25^\circ\text{C}$  and  $T_A = +105^\circ\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS		
V <sub>CORE</sub> Fixed Current, BACKUP Mode	I <sub>CORE_FBKUD</sub>	0KB SRAM retained, RTC disabled, retention regulator disabled	temperature variance.					
			V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 25</a> for temperature variance.		0.33			
			V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 25</a> for temperature variance.		0.18			
			V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 25</a> for temperature variance.		0.33			
		20KB SRAM retained with RTC disabled	V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 25</a> for temperature variance.		0.18			
			V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 25</a> for temperature variance.		1.28			
			V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 25</a> for temperature variance.		0.54			
			V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 25</a> for temperature variance.		1.28			
		40KB SRAM retained with RTC disabled	V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 25</a> for temperature variance.		0.54			
			V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 25</a> for temperature variance.		2.23			
				V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 25</a> for		0.9		

(Limits are 100% tested at  $T_A = +25^\circ\text{C}$  and  $T_A = +105^\circ\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
		temperature variance.				
		V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 25</a> for temperature variance.		2.23		
		V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 25</a> for temperature variance.		0.9		
		V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 25</a> for temperature variance.		3.2		
		V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 25</a> for temperature variance.		1.2		
		V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 25</a> for temperature variance.		3.2		
		V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 25</a> for temperature variance.		1.2		
		V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 25</a> for temperature variance.		4.1		
		V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 25</a> for temperature variance.		1.6		
		V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 25</a> for temperature variance.		4.1		
		V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 25</a> for		1.6		



(Limits are 100% tested at  $T_A = +25^\circ\text{C}$  and  $T_A = +105^\circ\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS		
		temperature variance.						
V <sub>DDIO</sub> Fixed Current, BACKUP Mode	I <sub>DDIO_FBKUD</sub>	0KB SRAM retained, RTC disabled, retention regulator disabled	V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 25</a> for temperature variance.		0.19		μA	
			V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 26</a> for temperature variance.		0.19			
			V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 26</a> for temperature variance.		0.05			
			V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 26</a> for temperature variance.		0.05			
		20KB SRAM retained with RTC disabled	V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 26</a> for temperature variance.		0.19			
			V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 26</a> for temperature variance.		0.19			
			V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 26</a> for temperature variance.		0.05			
			V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 26</a> for temperature variance.		0.05			
		40KB SRAM retained with RTC disabled	V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 26</a> for temperature variance.		0.19			
			V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 26</a> for		0.19			

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
		temperature variance.				
		V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 26</a> for temperature variance.		0.05		
		V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 26</a> for temperature variance.		0.05		
		V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 26</a> for temperature variance.		0.19		
		V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 26</a> for temperature variance.		0.19		
		V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 26</a> for temperature variance.		0.05		
		V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 26</a> for temperature variance.		0.05		
		V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 26</a> for temperature variance.		0.19		
		V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 26</a> for temperature variance.		0.19		
		V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 26</a> for temperature variance.		0.05		
		V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 26</a> for		0.05		

(Limits are 100% tested at  $T_A = +25^\circ\text{C}$  and  $T_A = +105^\circ\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
			temperature variance.				
V <sub>CORE</sub> Fixed Current, STORAGE Mode	I <sub>CORE_FSTOD</sub>	V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 27</a> for temperature variance.			0.33		μA
		V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 27</a> for temperature variance.			0.18		
		V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 27</a> for temperature variance.			0.33		
		V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 27</a> for temperature variance.			0.18		
V <sub>DDIO</sub> Fixed Current, STORAGE Mode	I <sub>DDIO_FSTOD</sub>	V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 28</a> for temperature variance.			0.22		μA
		V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 28</a> for temperature variance.			0.22		
		V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 1.1V. See <a href="#">Table 28</a> for temperature variance.			0.06		
		V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 0.855V. See <a href="#">Table 28</a> for temperature variance.			0.06		
<b>CLOCKS</b>							
System Clock Frequency	f <sub>SYS_CLK</sub>			0		f <sub>IPO</sub>	MHz
Internal Primary Oscillator (IPO)	f <sub>IPO</sub>	Default PWRSEQ_LPCTRL.ovr = 0b10			100		MHz
Internal Baud Rate Oscillator (IBRO)	f <sub>IBRO</sub>				7.3728		MHz
Internal Nanoring Oscillator (INRO)	f <sub>INRO</sub>	Measured at V <sub>DDIO</sub> = 1.8V			80		kHz
External RTC Oscillator (ERTCO)	f <sub>ERTCO</sub>	32kHz watch crystal, C <sub>L</sub> = 6pF, ESR < 90kΩ, C <sub>0</sub> ≤ 2pF			32.768		kHz
External RF Oscillator Frequency (ERFO)	f <sub>ERFO</sub>	32MHz crystal, CL = 12pF, ESR ≤ 50Ω, C <sub>0</sub> ≤ 7pF, temperature stability ±20ppm, initial tolerance ±20ppm			32		MHz
RTC Operating Current	I <sub>RTC</sub>	All power modes, RTC enabled			0.35		μA
RTC Power-up Time	t <sub>RTC_ON</sub>				250		ms
External System Clock Input Frequency	f <sub>EXT_CLK</sub>	HF_EXT_CLK selected, V <sub>DDIO</sub> ≥ 3.0V	Minimum voltage vs. frequency requirements for PWRSEQ_LPCTRL.ovr settings must be followed.			50	MHz
		HF_EXT_CLK selected, V <sub>DDIO</sub> < 3.0V	Minimum voltage vs. frequency requirements for PWRSEQ_LPCTRL.ovr settings must be followed.			25	
External Low-Power Timer Clock Input Frequency	f <sub>EXT_LPTMR_CLK</sub>	LP_EXT_CLK selected, V <sub>DDIO</sub> ≥ 3.0V				10	MHz
		LP_EXT_CLK selected, V <sub>DDIO</sub> < 3.0V				5	
<b>GENERAL-PURPOSE I/O</b>							

(Limits are 100% tested at  $T_A = +25^\circ\text{C}$  and  $T_A = +105^\circ\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Input Low Voltage for All GPIO, RSTN	$V_{IL\_GPIO}$	Pin configured as GPIO			$0.3 \times V_{DDIO}$	V
Input High Voltage for All GPIO, RSTN	$V_{IH\_GPIO}$	Pin configured as GPIO	$0.7 \times V_{DDIO}$			V
Output Low Voltage for All GPIO Except P0.6, P0.9, P0.12, and P0.13	$V_{OL\_GPIO}$	$V_{DDIO} = 1.71\text{V}$ , $I_{OL} = 1\text{mA}$ , DS[1:0] = 00 (Note 2)		0.2	0.4	V
		$V_{DDIO} = 1.71\text{V}$ , $I_{OL} = 2\text{mA}$ , DS[1:0] = 10 (Note 2)		0.2	0.4	
		$V_{DDIO} = 1.71\text{V}$ , $I_{OL} = 4\text{mA}$ , DS[1:0] = 01 (Note 2)		0.2	0.4	
		$V_{DDIO} = 1.71\text{V}$ , $I_{OL} = 6\text{mA}$ , DS[1:0] = 11 (Note 2)		0.2	0.4	
Output Low Voltage for GPIO P0.6, P0.9, P0.12, and P0.13	$V_{OL\_I2C}$	$V_{DDIO} = 1.71\text{V}$ , $I_{OL} = 2\text{mA}$ , DS = 0 (Note 2)		0.2	0.4	V
		$V_{DDIO} = 1.71\text{V}$ , $I_{OL} = 10\text{mA}$ , DS = 1 (Note 2)		0.2	0.4	
Output High Voltage for All GPIO Except P0.6, P0.9, P0.12, and P0.13	$V_{OH\_VGPIO}$	$V_{DDIO} = 1.71\text{V}$ , $I_{OH} = 1\text{mA}$ , DS[1:0] = 00 (Note 2)	$V_{DDIO} - 0.4$			V
		$V_{DDIO} = 1.71\text{V}$ , $I_{OH} = 2\text{mA}$ , DS[1:0] = 10 (Note 2)	$V_{DDIO} - 0.4$			
		$V_{DDIO} = 1.71\text{V}$ , $I_{OH} = 4\text{mA}$ , DS[1:0] = 01 (Note 2)	$V_{DDIO} - 0.4$			
		$V_{DDIO} = 1.71\text{V}$ , $I_{OH} = 6\text{mA}$ , DS[1:0] = 11 (Note 2)	$V_{DDIO} - 0.4$			
Output High Voltage for GPIO P0.6, P0.9, P0.12, and P0.13	$V_{OH\_I2C}$	$V_{DDIO} = 1.71\text{V}$ , $I_{OH} = 2\text{mA}$ , DS = 0 (Note 2)	$V_{DDIO} - 0.4$			V
		$V_{DDIO} = 1.71\text{V}$ , $I_{OH} = 10\text{mA}$ , DS = 1 (Note 2)	$V_{DDIO} - 0.4$			
Combined $I_{OL}$ , All GPIO	$I_{OL\_TOTAL}$				100	mA
Combined $I_{OH}$ , All GPIO	$I_{OH\_TOTAL}$		-100			mA
Input Hysteresis (Schmitt)	$V_{IHYS}$			300		mV
Input/Output Pin Capacitance for All Pins	$C_{IO}$			4		pF
Input Leakage Current Low	$I_{IL}$	$V_{IN} = 0\text{V}$ , internal pull-up disabled	-200		+200	nA
Input Leakage Current High	$I_{IH}$	$V_{IN} = 3.63\text{V}$ , internal pull-up disabled	-800		+800	nA
RSTN Assertion Time	$t_{RSTN}$	Device in ACTIVE mode, RSTN device pin assertion duration to entry into device reset state		$6 \times t_{SYS\_CL}$ K		$\mu\text{s}$
Input Pull-up Resistor RSTN	$R_{PU\_VDDIO}$	Internal pull-up to $V_{DDIO} = V_{RST}$ , RSTN at $V_{IH}$		18.7		k $\Omega$
		Internal pull-up to $V_{DDIO} = 3.63\text{V}$ , RSTN at $V_{IH}$		10.0		
Input Pull-up Resistor for All GPIO	$R_{PU}$	Device pin configured as GPIO, internal pull-up to $V_{DDIO} = V_{RST}$ . device pin at $V_{IH}$		18.7		k $\Omega$

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
		Device pin configured as GPIO, internal pull-up to $V_{DDIO} = 3.63\text{V}$ , device pin at $V_{IH}$		10.0		
Input Pull-down Resistor for All GPIO	$R_{PD}$	Device pin configured as GPIO, internal pull-down to $V_{SS}$ , $V_{DDIO} = V_{RST}$ , device pin at $V_{IL}$		17.6		k $\Omega$
		Device pin configured as GPIO, internal pull-down to $V_{SS}$ , $V_{DDIO} = V_{RST}$ , device pin at $V_{IL}$		8.8		
<b>12-BIT SAR ADC</b>						
$V_{DDA}$ Standby Current	$I_{VDDA}$	ADC_CTRL0.reset b = 0, ADC_CTRL0.bias_en = 0, ADC_CTRL0.adc_en = 0 MCR_ADCCFG1.amp_en = 0 MCR_ADCCFG1.in_inp_en = 0b1111, input buffer disabled	$V_{DDA} = 1.8\text{V}$	340		$\mu\text{A}$
			$V_{DDA} = 3.3\text{V}$	361		
$V_{DDA}$ ADC Active Current	$I_{ADC}$	ADC Active, reference buffer disabled, ADC clock = 25MHz. Additional current above $I_{VDDA}$ .	MCR_ADCCFG0.ext_ref = 0, MCR_ADCCFG0.int_ref = 0, $V_{DDA} = 1.8\text{V}$	202		$\mu\text{A}$
			MCR_ADCCFG0.ext_ref = 0, MCR_ADCCFG0.int_ref = 1, $V_{DDA} = 3.3\text{V}$	353		
		ADC Active, reference buffer disabled, ADC clock = 16MHz. Additional current above $I_{VDDA}$ .	MCR_ADCCFG0.ext_ref = 0, MCR_ADCCFG0.int_ref = 0, $V_{DDA} = 1.8\text{V}$	167		
			MCR_ADCCFG0.ext_ref = 0, MCR_ADCCFG0.int_ref = 1, $V_{DDA} = 3.3\text{V}$	280		
Bandgap Temperature Coefficient	$V_{TEMPCO}$	Box method		$\pm 25$		ppm
<b>12-BIT SAR ADC/INPUT BUFFER ENABLED (MCR_ADCCFG1.thru_pad_sw_en = 1; MCR_ADCCFG1.thru_en = 1; MCR_ADCCFG1.amp_en = 1)</b>						
Resolution				12		bits
Effective Number of Bits	ENOB	ADC_CLKCTRL.clkdiv = 0b000. AINx input pk-pk = $V_{REF} - 10\text{mV}$		10		bits
External Reference Voltage	$V_{REF}$	$V_{REF} \leq V_{DDA}$ ,	2.048		$V_{DDA}$	V

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
		MCR_ADCCFG0.ext_ref = 1, MCR_ADCCFG1.ain_inp_en = 0b0001					
Internal Reference Voltage	$V_{\text{INT\_REF}}$	MCR_ADCCFG0.ext_ref = 0, MCR_ADCCFG0.int_ref = 0			1.25		V
		MCR_ADCCFG0.ext_ref = 0, MCR_ADCCFG0.int_ref = 1			2.048		
ADC Clock Rate Maximum	$f_{\text{ACLK}}$				25		MHz
Input Voltage Range	$V_{\text{AIN}}$	AIN[3:0], ADC_DATA.chan = [3:0]	MCR_ADCCFG1.di vsel = 0b00	$V_{\text{SSA}} + 0.05$		MIN( $V_{\text{REF}}$ , $V_{\text{DDIOH}}$ )	V
			MCR_ADCCFG1.di vsel = 0b01	$V_{\text{SSA}} + 0.05$		MIN( $V_{\text{REF}}$ , $V_{\text{DDIOH}}$ )	
			MCR_ADCCFG1.di vsel = 0b10	$V_{\text{SSA}} + 0.05$		MIN( $2 \times V_{\text{REF}}$ , $V_{\text{DDIOH}}$ )	
			MCR_ADCCFG1.di vsel = 0b11	$V_{\text{SSA}} + 0.05$		MIN( $3 \times V_{\text{REF}}$ , $V_{\text{DDIOH}}$ )	
ADC Buffer Current	$I_{\text{ADCBUFFER}}$				54		$\mu\text{A}$
Input Impedance	$R_{\text{AIN}}$				100		k $\Omega$
Analog Input Capacitance	$C_{\text{AIN}}$	Fixed capacitance to $V_{\text{SSA}}$			2		pF
Integral Nonlinearity	INL				$\pm 1.5$		LSb
Differential Nonlinearity	DNL				$\pm 0.75$		LSb
Offset Error	$V_{\text{OS}}$	Chopping enabled			$\pm 0.25$		LSb
ADC Input Buffer Offset	$V_{\text{OS}}$				$\pm 1.5$		LSb
ADC Sample Rate	$f_{\text{ADC}}$					25	kHz
ADC Setup Time	$t_{\text{ADC\_SU}}$	Any power-up of ADC clock or ADC bias to CpuAdcStart				500	$\mu\text{s}$
ADC Input Leakage	$I_{\text{ADC\_LEAK}}$				$\pm 1.2$		nA
<b>12-BIT SAR ADC/INPUT BUFFER DISABLED (MCR_ADCCFG1.thru_pad_sw_enx = 0; MCR_ADCCFG1.thru_en = 0; MCR_ADCCFG1.amp_en = 0)</b>							
Resolution					12		bits
Effective Number of Bits	ENOB	ADC_CLKCTRL.clkdiv = 0b000. AINx input pk-pk = $V_{\text{REF}} - 10\text{mV}$			10		bits
External Reference Voltage	$V_{\text{REF}}$	$V_{\text{REF}} \leq V_{\text{DDA}}$ , MCR_ADCCFG0.ext_ref = 1		2.048		$V_{\text{DDA}}$	V
Internal Reference Voltage	$V_{\text{INT\_REF}}$	MCR_ADCCFG0.ext_ref = 0, MCR_ADCCFG0.int_ref = 0			1.25		V
		MCR_ADCCFG0.ext_ref = 0, MCR_ADCCFG0.int_ref = 1			2.048		
ADC Clock Rate Maximum	$f_{\text{ACLK}}$				25		MHz
Input Voltage Range	$V_{\text{AIN}}$	AIN[3:0], ADC_DATA.chan = [3:0]	MCR_ADCCFG1.di vsel = 0b00	$V_{\text{SSA}} + 0.05$		$V_{\text{REF}}$	V

(Limits are 100% tested at  $T_A = +25^{\circ}\text{C}$  and  $T_A = +105^{\circ}\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Input Impedance	$R_{AIN}$			1.2		$M\Omega$
Analog Input Capacitance	$C_{AIN}$	Fixed capacitance to $V_{SSA}$		2		pF
		Dynamically switched capacitance		1.2		
Integral Nonlinearity	INL			$\pm 1.5$		LSb
Differential Nonlinearity	DNL			$\pm 0.75$		LSb
Offset Error	$V_{OS}$	Chopping enabled		$\pm 0.25$		LSb
ADC Sample Rate	$f_{ADC}$				1	Msp/s
ADC Setup Time	$t_{ADC\_SU}$	Any power-up of ADC clock or ADC bias to CpuAdcStart			500	$\mu\text{s}$
ADC Input Leakage	$I_{ADC\_LEAK}$	ADC inactive or channel not selected		$\pm 1.2$		nA
<b>COMPARATORS</b>						
Input Offset Voltage	$V_{OFFSET}$			$\pm 1$		mV
Input Hysteresis	$V_{HYST}$	AINCOMPHYST[1:0] = 00		$\pm 23$		mV
		AINCOMPHYST[1:0] = 01		$\pm 50$		
		AINCOMPHYST[1:0] = 10		$\pm 2$		
		AINCOMPHYST[1:0] = 11		$\pm 7$		
Input Voltage Range	$V_{IN\_CMP}$	Common-mode range	0		$V_{DDIO}$	V
<b>FLASH MEMORY</b>						
Flash Erase Time	$t_{M\_ERASE}$	Mass erase		20		ms
	$t_{P\_ERASE}$	Page erase		20		
Flash Programming Time per Word	$t_{PROG}$			42		$\mu\text{s}$
Flash Endurance			10			kcycles
Data Retention	$t_{RET}$	$T_A = +125^{\circ}\text{C}$	10			years

**Note 2:** When using a GPIO bias voltage of 2.97V, the drive current capability of the GPIO is 2x that of its drive strength when using a GPIO bias voltage of 1.71V.

## Electrical Characteristics – I<sup>2</sup>C

(Timing specifications are guaranteed by design and not production tested.  $T_A = -40^{\circ}\text{C}$  to  $+105^{\circ}\text{C}$ )

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>STANDARD-MODE</b>						
Output Fall Time	$t_{OF}$	Standard-mode, from $V_{IH(MIN)}$ to $V_{IL(MAX)}$		150		ns
SCL Clock Frequency	$f_{SCL}$		0		100	kHz
Low Period SCL Clock	$t_{LOW}$		4.7			$\mu\text{s}$
High Time SCL Clock	$t_{HIGH}$		4.0			$\mu\text{s}$
Setup Time for Repeated Start Condition	$t_{SU;STA}$		4.7			$\mu\text{s}$
Hold Time for Repeated Start Condition	$t_{HD;STA}$		4.0			$\mu\text{s}$

(Timing specifications are guaranteed by design and not production tested.  $T_A = -40^{\circ}\text{C}$  to  $+105^{\circ}\text{C}$ )

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Data Setup Time	$t_{\text{SU;DAT}}$			300		ns
Data Hold Time	$t_{\text{HD;DAT}}$			10		ns
Rise Time for SDA and SCL	$t_{\text{R}}$			800		ns
Fall Time for SDA and SCL	$t_{\text{F}}$			200		ns
Setup Time for a Stop Condition	$t_{\text{SU;STO}}$		4.0			$\mu\text{s}$
Bus Free Time Between a Stop and Start Condition	$t_{\text{BUS}}$		4.7			$\mu\text{s}$
Data Valid Time	$t_{\text{VD;DAT}}$		3.45			$\mu\text{s}$
Data Valid Acknowledge Time	$t_{\text{VD;ACK}}$		3.45			$\mu\text{s}$
<b>FAST-MODE</b>						
Output Fall Time	$t_{\text{OF}}$	From $V_{\text{IH(MIN)}}$ to $V_{\text{IL(MAX)}}$		150		ns
Pulse Width Suppressed by Input Filter	$t_{\text{SP}}$			75		ns
SCL Clock Frequency	$f_{\text{SCL}}$		0		400	kHz
Low Period SCL Clock	$t_{\text{LOW}}$		1.3			$\mu\text{s}$
High Time SCL Clock	$t_{\text{HIGH}}$		0.6			$\mu\text{s}$
Setup Time for Repeated Start Condition	$t_{\text{SU;STA}}$		0.6			$\mu\text{s}$
Hold Time for Repeated Start Condition	$t_{\text{HD;STA}}$		0.6			$\mu\text{s}$
Data Setup Time	$t_{\text{SU;DAT}}$			125		ns
Data Hold Time	$t_{\text{HD;DAT}}$			10		ns
Rise Time for SDA and SCL	$t_{\text{R}}$			30		ns
Fall Time for SDA and SCL	$t_{\text{F}}$			30		ns
Setup Time for a Stop Condition	$t_{\text{SU;STO}}$		0.6			ms
Bus Free Time Between a Stop and Start Condition	$t_{\text{BUS}}$		1.3			$\mu\text{s}$
Data Valid Time	$t_{\text{VD;DAT}}$		0.9			$\mu\text{s}$
Data Valid Acknowledge Time	$t_{\text{VD;ACK}}$		0.9			$\mu\text{s}$
<b>FAST-MODE PLUS</b>						
Output Fall Time	$t_{\text{OF}}$	From $V_{\text{IH(MIN)}}$ to $V_{\text{IL(MAX)}}$		80		ns
Pulse Width Suppressed by Input Filter	$t_{\text{SP}}$			75		ns
SCL Clock Frequency	$f_{\text{SCL}}$		0		1000	kHz
Low Period SCL Clock	$t_{\text{LOW}}$		0.5			$\mu\text{s}$



(Timing specifications are guaranteed by design and not production tested.  $T_A = -40^{\circ}\text{C}$  to  $+105^{\circ}\text{C}$ )

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
High Time SCL Clock	$t_{\text{HIGH}}$		0.26			$\mu\text{s}$
Setup Time for Repeated Start Condition	$t_{\text{SU;STA}}$		0.26			$\mu\text{s}$
Hold Time for Repeated Start Condition	$t_{\text{HD;STA}}$		0.26			$\mu\text{s}$
Data Setup Time	$t_{\text{SU;DAT}}$			50		ns
Data Hold Time	$t_{\text{HD;DAT}}$			10		ns
Rise Time for SDA and SCL	$t_{\text{R}}$			50		ns
Fall Time for SDA and SCL	$t_{\text{F}}$			30		ns
Setup Time for a Stop Condition	$t_{\text{SU;STO}}$		0.26			$\mu\text{s}$
Bus Free Time Between a Stop and Start Condition	$t_{\text{BUS}}$		0.5			$\mu\text{s}$
Data Valid Time	$t_{\text{VD;DAT}}$		0.45			$\mu\text{s}$
Data Valid Acknowledge Time	$t_{\text{VD;ACK}}$		0.45			$\mu\text{s}$

## Electrical Characteristics – I<sup>2</sup>S

(Timing specifications are guaranteed by design and not production tested.  $T_A = -40^{\circ}\text{C}$  to  $+105^{\circ}\text{C}$ )

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>TARGET MODE</b>						
Bit Clock Frequency	$f_{\text{BCLKS}}$				25	MHz
Bit Clock Period	$t_{\text{BCLKS}}$		$1/f_{\text{BCLKS}}$			ns
BCLK High Time	$t_{\text{WBCLKHS}}$			0.5		$1/f_{\text{BCLKS}}$
BCLK Low Time	$t_{\text{WBCLKLS}}$			0.5		$1/f_{\text{BCLKS}}$
LRCLK Setup Time	$t_{\text{LRCLK\_BCLKS}}$			25		ns
Delay Time, BCLK to SD (Output) Valid	$t_{\text{BCLK\_SDOS}}$			12		ns
Setup Time for SD (Input)	$t_{\text{SU\_SDIS}}$			6		ns
Hold Time SD (Input)	$t_{\text{HD\_SDIS}}$			3		ns
<b>CONTROLLER MODE</b>						
Bit Clock Frequency	$f_{\text{BCLKM}}$	Source only from ERFO			32	MHz
Bit Clock Period	$t_{\text{BCLKM}}$		$1/f_{\text{BCLKM}}$			ns
BCLK High Time	$t_{\text{WBCLKHM}}$			0.5		$1/f_{\text{BCLKM}}$
BCLK Low Time	$t_{\text{WBCLKLM}}$			0.5		$1/f_{\text{BCLKM}}$
Delay Time BCLK to LRCLK Valid	$t_{\text{LRCLK\_BCLKM}}$			20		ns
Delay Time, BCLK to SD (Output) Valid	$t_{\text{BCLK\_SDOM}}$			20		ns
Setup Time for SD (Input)	$t_{\text{SU\_SDIM}}$			10		ns

(Timing specifications are guaranteed by design and not production tested.  $T_A = -40^{\circ}\text{C}$  to  $+105^{\circ}\text{C}$ )

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Hold Time SD (Input)	$t_{HD\_SDIM}$			10		ns

## Electrical Characteristics – SPI

(Timing specifications are guaranteed by design and not production tested.  $T_A = -40^{\circ}\text{C}$  to  $+105^{\circ}\text{C}$ )

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>CONTROLLER MODE</b>						
SPI Controller Operating Frequency	$f_{MCK}$	$f_{SYS\_CLK} = 100\text{MHz}$ , $f_{MCK(MAX)} = f_{SYS\_CLK}/2$			50	MHz
SPI Controller SCK Period	$t_{MCK}$			$1/f_{MCK}$		ns
SCK Output Pulse-Width High/Low	$t_{MCH}$ , $t_{MCL}$		$t_{MCK}/2$			ns
MOSI Output Hold Time After SCK Sample Edge	$t_{MOH}$		$t_{MCK}/2$			ns
MOSI Output Valid to Sample Edge	$t_{MOV}$		$t_{MCK}/2$			ns
MOSI Output Hold Time After SCK Low Idle	$t_{MLH}$			$t_{MCK}/2$		ns
MISO Input Valid to SCK Sample Edge Setup	$t_{MIS}$			5		ns
MISO Input to SCK Sample Edge Hold	$t_{MIH}$			$t_{MCK}/2$		ns
<b>TARGET MODE</b>						
SPI Target Operating Frequency	$f_{SCK}$				50	MHz
SPI Target SCK Period	$t_{SCK}$			$1/f_{SCK}$		ns
SCK Input Pulse-Width High/Low	$t_{SCH}$ , $t_{SCL}$			$t_{SCK}/2$		ns
SSx Active to First Shift Edge	$t_{SSE}$			10		ns
MOSI Input to SCK Sample Edge Rise/Fall Setup	$t_{SIS}$			5		ns
MOSI Input from SCK Sample Edge Transition Hold	$t_{SIH}$			1		ns
MISO Output Valid After SCLK Shift Edge Transition	$t_{SOV}$			5		ns
SCK Inactive to SSx Inactive	$t_{SSD}$			10		ns
SSx Inactive Time	$t_{SSH}$			$1/f_{SCK}$		$\mu\text{s}$
MISO Hold Time After SSx Deassertion	$t_{SLH}$			$1/f_{SCK}$		ns

## Timing Diagrams

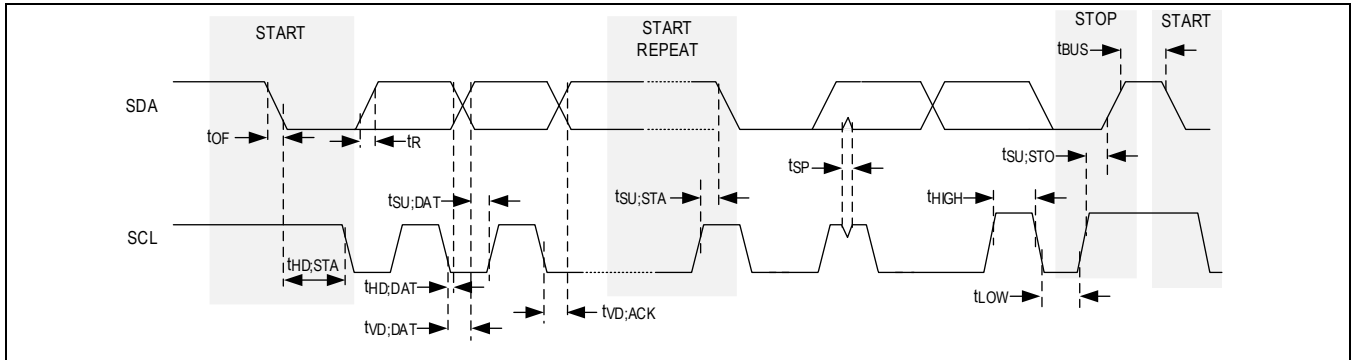


Figure 1. I<sup>2</sup>C Timing Diagram

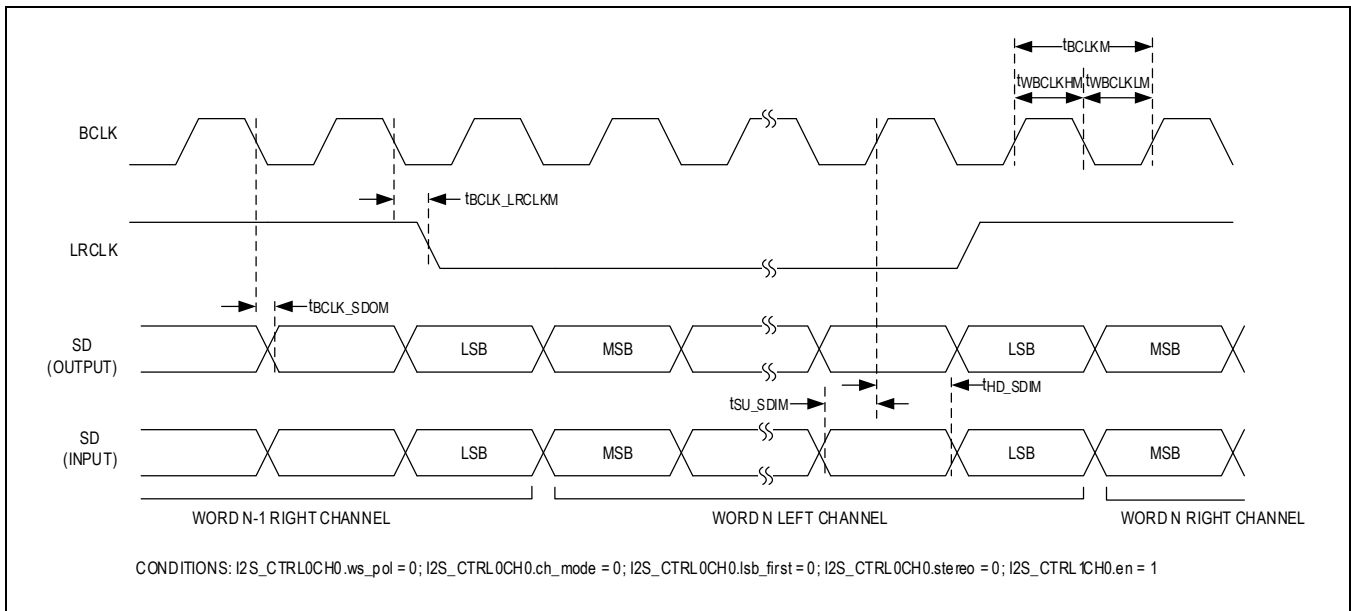


Figure 2. I<sup>2</sup>S Controller Timing Diagram

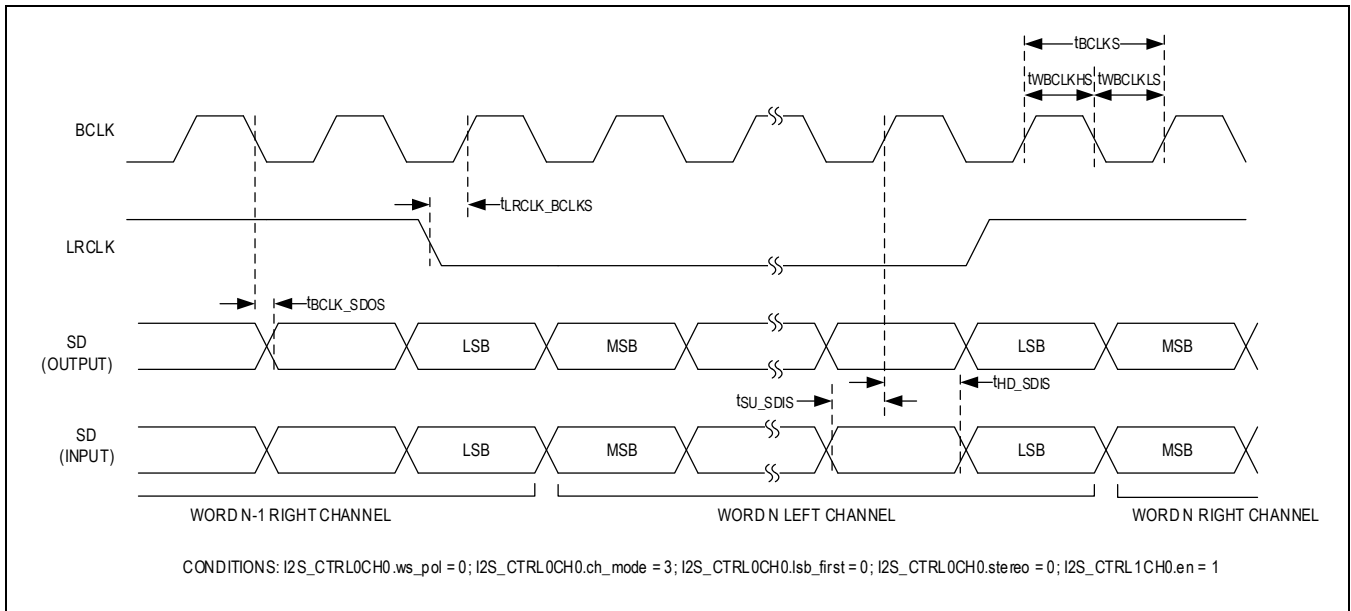


Figure 3. I2S Target Timing Diagram

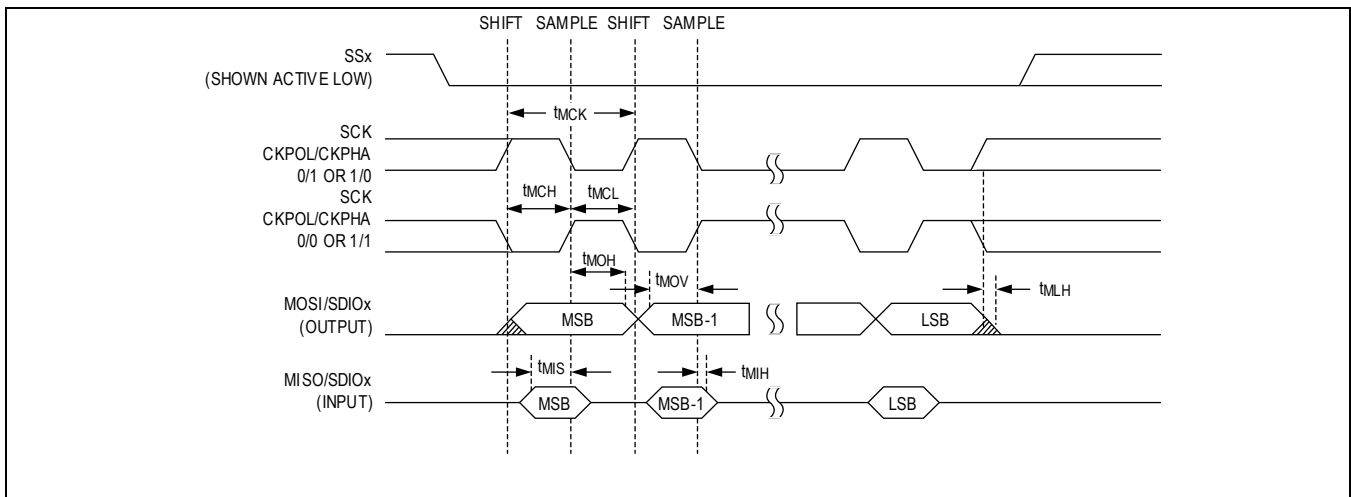


Figure 4. SPI Controller Mode Timing Diagram

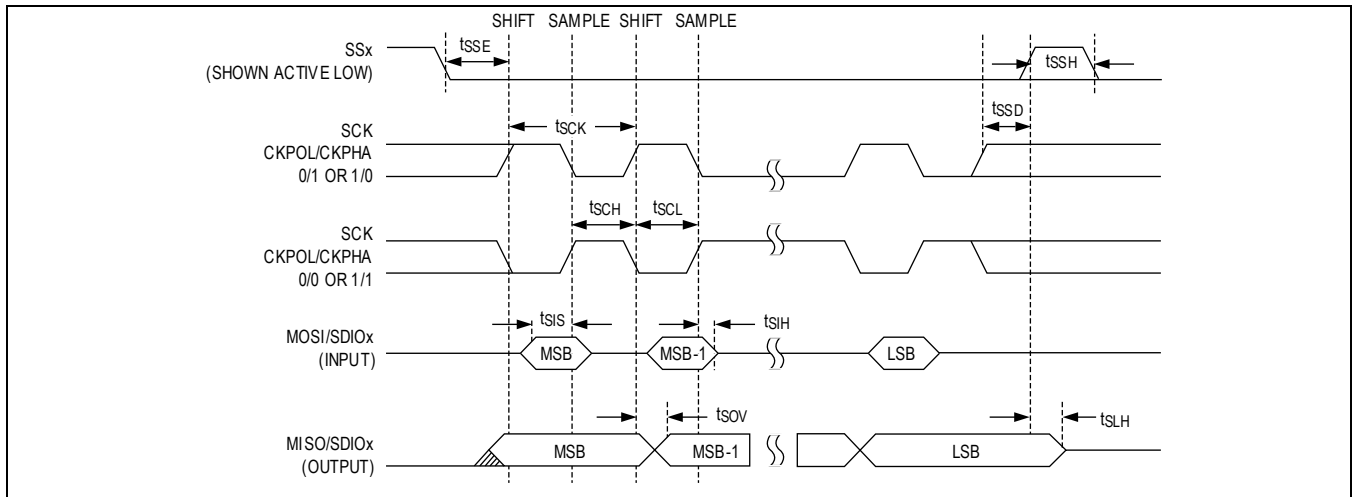
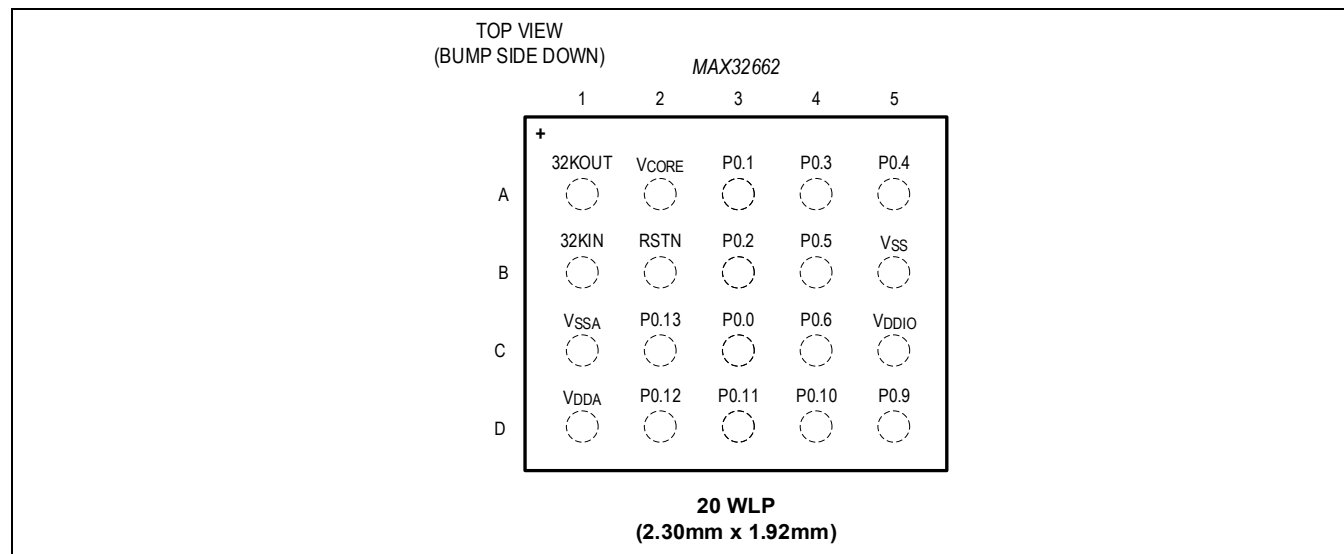


Figure 5. SPI Target Mode Timing Diagram

## Pin Configuration – 20 WLP



## Pin Descriptions – 20 WLP

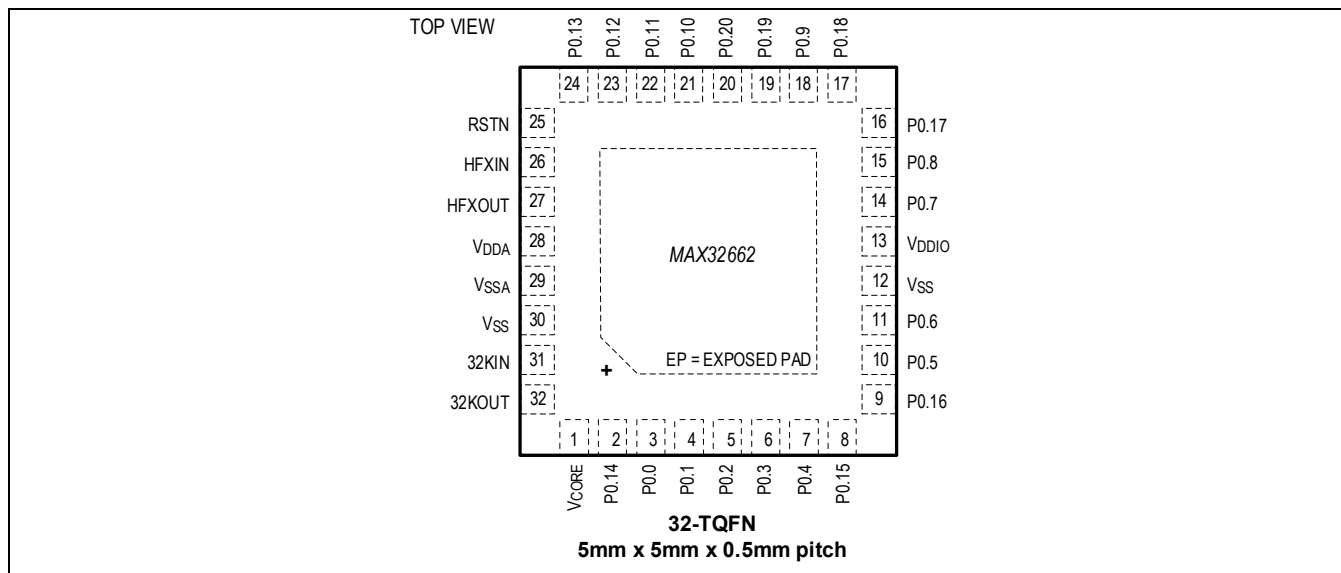
PIN	NAME	FUNCTION MODES						FUNCTION
		Primary Signal (Default)	Alternative Function 1	Alternative Function 2	Alternative Function 3	Alternative Function 4	Alternative Function 5	
<b>POWER</b>								
A2	V <sub>CORE</sub>	—	—	—	—	—	—	Digital Supply Voltage. Bypass with 1µF to V <sub>SS</sub> .
C5	V <sub>DDIO</sub>	—	—	—	—	—	—	GPIO Supply Voltage. Bypass with 1µF to V <sub>SS</sub> . This pin must be connected to the V <sub>DDA</sub> device pin at the PCB level.
D1	V <sub>DDA</sub>	—	—	—	—	—	—	Analog Supply Voltage. Bypass this pin to V <sub>SSA</sub> with 1µF. This pin must be connected to the V <sub>DDIO</sub> device pin at the PCB level.
C1	V <sub>SSA</sub>	—	—	—	—	—	—	Analog Ground
B5	V <sub>SS</sub>	—	—	—	—	—	—	Digital Ground
<b>RESET AND CONTROL</b>								
B2	RSTN	—	—	—	—	—	—	Active-Low, External System Reset Input. The device remains in reset while this pin is in its active state. When the pin transitions to its inactive state, the device performs a system reset and begins execution. This pin has an internal pull-up, R <sub>PU</sub> V <sub>DDIO</sub> , to the V <sub>DDIO</sub> supply.
<b>CLOCK</b>								

PIN	NAME	FUNCTION MODES						FUNCTION
		Primary Signal (Default)	Alternate Function 1	Alternate Function 2	Alternate Function 3	Alternate Function 4	Alternate Function 5	
A1	32KOUT	—	—	—	—	—	—	32kHz Crystal Oscillator Output. Refer to the <a href="#">MAX32662 User Guide</a> for determination of the required external stability capacitors.
B1	32KIN	—	—	—	—	—	—	32kHz Crystal Oscillator Input. Connect a 32kHz crystal between 32KIN and 32KOUT for RTC operation. Refer to the <a href="#">MAX32662 User Guide</a> for determination of the required external stability capacitors. Optionally, this pin can be configured as the input for an external CMOS-level clock source.
<b>GPIO AND ALTERNATE FUNCTION</b>								
C3	P0.0	P0.0	SWDIO	PT0B	TMR0C_OA	TMR1D_OA	ADC_TRIGGER_E	Serial-Wire Debug I/O; Pulse Train 0 Port Map B; TMR0 Output 32 Bits or Lower 16 Bits Port Map C; TMR1 Output 32 Bits or Lower 16 Bits Port Map D; ADC Trigger Input Port Map E
A3	P0.1	P0.1	SWCLK	PT1B	TMR0C_IA	TMR1D_IA	—	Serial-Wire Debug Clock; Pulse Train 1 Port Map B; TMR0 Input 32 Bits or Lower 16 Bits Port Map C; TMR1 Input 32 Bits or Lower 16 Bits Port Map D
B3	P0.2	P0.2	SPI0A_CITO	UART1B_TX	TMR0C_IA	PT0D	I2S0E_SDO	SPI0 Controller In Target Out Port Map A; UART1 Transmit Port Map B; TMR0 Input 32 Bits or Lower 16 Bits Port Map C; Pulse Train 0 Port Map D; I2S0 Serial Data Output Port Map E
A4	P0.3	P0.3	SPI0A_COPI	UART1B_RX	TMR0C_OA	PT1D	I2S0E_SDI	SPI0 Controller Out Target In Port Map A; UART1 Receive Port Map B; TMR0 Output 32 Bits or Lower 16 Bits Port Map C; Pulse Train 1 Port Map D; I2S0 Serial Data Input Port Map E
A5	P0.4	P0.4	SPI0A_SCK	UART1B_CTS	TMR1C_IA	PT2D	I2S0E_BCLK	SPI0 Serial Clock Port Map A; UART1 CTS Port Map B; TMR1 Input 32 Bits or Lower 16 Bits Port Map C; Pulse Train 2 Port Map D; I2S0 Bit Clock Port Map E
B4	P0.5	P0.5	SPI0A_TS0	UART1B_RTS	TMR1C_OA	PT3D	I2S0E_LRCLK	SPI0 Target Select 0 Port Map A; UART1 RTS Port Map B; TMR1 Output 32 Bits or Lower 16 Bits Port Map C; Pulse Train 3 Port Map D; I2S0 Left/Right Clock Port Map E
C4	P0.6	P0.6 (SCPBL default)	I2C1A_SCL	CAN0B_RX	TMR2C_IA	HF_EXT_CLK	PT2E	I2C1 SCL Port Map A; CAN Receive Port Map B; TMR2 Input 32 Bits or Lower 16 Bits Port Map C; External Clock Input; Pulse Train 2 Port Map

PIN	NAME	FUNCTION MODES						FUNCTION
		Primary Signal (Default)	Alternate Function 1	Alternate Function 2	Alternate Function 3	Alternate Function 4	Alternate Function 5	
		stimulus pin)						E. See <a href="#">Bootloader Activation</a> for more information.
D5	P0.9	P0.9	I2C1A_SDA	CAN0B_TX	TMR2C_OA	ADC_T RIG_D	PT3E	I2C1 SDA Port Map A; CAN Transmit Port Map B; TMR2 Output 32 Bits or Lower 16 Bits Port Map C; ADC Trigger Input Port Map D; Pulse Train 3 Port Map E
D4	P0.10	P0.10	UART0 A_TX	SPI1B_TS0	—	AIN3/AI N_C0_P /AIN_C1 _P	—	UART0 Transmit Port Map A; SPI1 Target Select 0 Port Map B; ADC Input 3/Comparator 0/1 Positive Input
D3	P0.11	P0.11	UART0 A_RX	SPI1B_SCK	32KCAL	AIN2/AI N_C0_P /AIN_C1 _P	LP_EXT _CLK	UART0 Receive Port Map A; SPI1 Serial Clock Port Map B; 32.768kHz Calibration Output; ADC Input 2/Comparator 0/1 Positive Input; LPTMR0 External Clock Input
D2	P0.12	P0.12	I2C0A_SCL	SPI1B_COTI	LPTMR 0C_IA	AIN1/AI N_C0_N /AIN_C1 _N	LPTMR 0E_OA N	I2C0 SCL Port Map A; SPI1 Controller Out Target In Port Map B; LPTMR0 Input 32 Bits or Lower 16 Bits Port Map C; ADC Input 1/Comparator 0/1 Negative Input; LPTMR0 Inverted Output 32 Bits or Lower 16 Bits Port Map E
C2	P0.13	P0.13	I2C0A_SDA	SPI1B_CITO	LPTMR 0C_OA	AIN0/VR EF/AIN_ C0_N/AI N_C1_N	—	I2C0 SDA Port Map A; SPI1 Controller In Target Out Port Map B; LPTMR0 Output 32 Bits or Lower 16 Bits Port Map C; ADC Input 0/Comparator 0/1 Negative Input; ADC Reference. When used as $V_{REF}$ for the ADC, requires 1 $\mu$ F bypass to $V_{SSA}$ and AIN0 is not available.



## Pin Configuration – 32 TQFN



## Pin Descriptions – 32 TQFN

PIN	NAME	FUNCTION MODES						FUNCTION
		Primary Signal (Default)	Alternate Function 1	Alternate Function 2	Alternate Function 3	Alternate Function 4	Alternate Function 5	
<b>POWER</b>								
1	V <sub>CORE</sub>	—	—	—	—	—	—	Digital Supply Voltage. Bypass with 1μF to V <sub>SS</sub> .
13	V <sub>DDIO</sub>	—	—	—	—	—	—	GPIO Supply Voltage. Bypass with 1μF to V <sub>SS</sub> . This pin must be connected to the V <sub>DDA</sub> device pin at the PCB level.
28	V <sub>DDA</sub>	—	—	—	—	—	—	Analog Supply Voltage. This pin must be connected to the V <sub>DDIO</sub> device pin at the PCB level. Bypass this pin to V <sub>SSA</sub> with 1μF.
29	V <sub>SSA</sub>	—	—	—	—	—	—	Analog Ground
12, 30	V <sub>SS</sub>	—	—	—	—	—	—	Digital Ground
EP	V <sub>SS</sub>	—	—	—	—	—	—	Digital Ground. Exposed pad. This pad must be connected to V <sub>SS</sub> . Refer to the <a href="#">MAX32662 User Guide</a> for additional information.
<b>RESET AND CONTROL</b>								
25	RSTN	—	—	—	—	—	—	Active-Low, External System Reset Input. The device remains in reset while this pin is in its active state. When the pin transitions to its inactive state,

PIN	NAME	FUNCTION MODES						FUNCTION
		Primary Signal (Default)	Alternate Function 1	Alternate Function 2	Alternate Function 3	Alternate Function 4	Alternate Function 5	
								the device performs a system reset and begins execution. This pin has an internal pull-up, R <sub>PU_VDDIO</sub> , to the V <sub>DDIO</sub> supply.
<b>CLOCK</b>								
32	32KOUT	—	—	—	—	—	—	32kHz Crystal Oscillator Output. Refer to the <a href="#">MAX32662 User Guide</a> for determination of the required external stability capacitors.
31	32KIN	—	—	—	—	—	—	32kHz Crystal Oscillator Input. Connect a 32kHz crystal between 32KIN and 32KOUT for RTC operation. Refer to the <a href="#">MAX32662 User Guide</a> for determination of the required external stability capacitors. Optionally, this pin can be configured as the input for an external CMOS-level clock source.
26	HFXIN	—	—	—	—	—	—	High-Frequency Crystal Oscillator Input. Connect a crystal between HFXIN and HFXOUT. Refer to the <a href="#">MAX32662 User Guide</a> for determination of the required external stability capacitors. Optionally, this pin can be configured as the input for an external square-wave source.
27	HFXOUT	—	—	—	—	—	—	High-Frequency Crystal Oscillator Output. Connect a crystal between HFXIN and HFXOUT. Refer to the <a href="#">MAX32662 User Guide</a> for determination of the required external stability capacitors.
<b>GPIO AND ALTERNATE FUNCTION</b>								
3	P0.0	P0.0	SWDIO	PT0B	TMR0C_OA	TMR1D_OA	ADC_TRIG_E	Serial Wire Debug I/O; Pulse Train 0 Port Map B; TMR0 Output 32 Bits or Lower 16 Bits Port Map C; TMR1 Output 32 Bits or Lower 16 Bits Port Map D; ADC Trigger Input Port Map E
4	P0.1	P0.1	SWDCLK	PT1B	TMR0C_I A	TMR1D_I A	—	Serial Wire Debug Clock; Pulse Train 1 Port Map B; TMR0 Input 32 Bits or Lower 16 Bits Port Map C; TMR1 Input 32 Bits or Lower 16 Bits Port Map D

PIN	NAME	FUNCTION MODES						FUNCTION
		Primary Signal (Default)	Alternate Function 1	Alternate Function 2	Alternate Function 3	Alternate Function 4	Alternate Function 5	
5	P0.2	P0.2	SPI0A_CIT TO	UART1B_ TX	TMR0C_I A	PT0D	I2S0E_S DO	SPI0 Controller In Target Out Port Map A; UART1 Transmit Port Map B; TMR0 Input 32 Bits or Lower 16 Bits Port Map C; Pulse Train 0 Port Map D; I2S0 Serial Data Output Port Map E
6	P0.3	P0.3	SPI0A_C OTI	UART1B_ RX	TMR0C_ OA	PT1D	I2S0E_S DI	SPI0 Controller Out Target In Port Map A; UART1 Receive Port Map B; TMR0 Output 32 Bits or Lower 16 Bits Port Map C; Pulse Train 1 Port Map D; I2S0 Serial Data Input Port Map E
7	P0.4	P0.4	SPI0A_S CK	UART1B_ CTS	TMR1C_I A	PT2D	I2S0E_B CLK	SPI0 Serial Clock Port Map A; UART1 CTS Port Map B; TMR1 Input 32 Bits or Lower 16 Bits Port Map C; Pulse Train 2 Port Map D; I2S0 Bit Clock Port Map E
10	P0.5	P0.5	SPI0A_T S0	UART1B_ RTS	TMR1C_ OA	PT3D	I2S0E_L RCLK	SPI0 Target Select 0 Port Map A; UART1 RTS Port Map B; TMR1 Output 32 Bits or Lower 16 Bits Port Map C; Pulse Train 3 Port Map D; I2S0 Left/Right Clock Port Map E
11	P0.6	P0.6 (SCPBL default stimulus pin)	I2C1A_S CL	CAN0B_ RX	TMR2C_I A	HF_EXT_ CLK	PT2E	I2C1 SCL Port Map A; CAN Receive Port Map B; TMR2 Input 32 Bits or Lower 16 Bits Port Map C; External Clock Input; Pulse Train 2 Port Map E. See <a href="#">Bootloader Activation</a> for more information.
14	P0.7	P0.7	SPI1A_C TO	UART0B_ CTS	TMR2C_I A	UART0D _RX	—	SPI1 Controller In Target Out Port Map A; UART0 CTS Port Map B; TMR2 Input 32 Bits or Lower 16 Bits Port Map C; UART0 Receive Port Map D
15	P0.8	P0.8	SPI1A_C OTI	UART0B_ RTS	TMR2C_ OA	UART0D _TX	—	SPI1 Controller Out Target In Port Map A; UART0 RTS Port Map B; TMR2 Output 32 Bits or Lower 16 Bits Port Map C; UART0 Transmit Port Map D
18	P0.9	P0.9	I2C1A_S DA	CAN0B_T X	TMR2C_ OA	ADC_TRI G_D	PT3E	I2C1 SDA Port Map A; CAN Transmit Port Map B; TMR2 Output 32 Bits or Lower 16 Bits Port Map C; ADC Trigger Input Port Map D; Pulse Train 3 Port Map E
21	P0.10	P0.10	UART0A_ TX	SPI1B_T S0	—	AIN3/AIN _C0_P/AI N_C1_P	—	UART0 Transmit Port Map A; SPI1 Target Select 0 Port Map B; ADC Input 3/Comparator 0/1 Positive Input

PIN	NAME	FUNCTION MODES						FUNCTION
		Primary Signal (Default)	Alternate Function 1	Alternate Function 2	Alternate Function 3	Alternate Function 4	Alternate Function 5	
22	P0.11	P0.11	UART0A_RX	SPI1B_SCK	32KCAL	AIN2/AIN_C0_P/AIN_C1_P	LP_EXT_CLK	UART0 Receive Port Map A; SPI1 Serial Clock Port Map B; 32.768kHz Calibration Output; ADC Input 2/Comparator 0/1 Positive Input; LPTMR0 External Clock Input
23	P0.12	P0.12	I2C0A_SCL	SPI1B_COTI	LPTMR0_C_IA	AIN1/AIN_C0_N/AIN_C1_N	LPTMR0_E_OAN	I2C0 SCL Port Map A; SPI1 Controller Out Target In Port Map B; LPTMR0 Input 32 Bits or Lower 16 Bits Port Map C; ADC Input 1/Comparator 0/1 Negative Input; LPTMR0 Inverted Output 32 Bits or Lower 16 Bits Port Map E
24	P0.13	P0.13	I2C0A_SDA	SPI1B_CITO	LPTMR0_C_OA	AIN0/VREF/AIN_C0_N/AIN_C1_N	—	I2C0 SDA Port Map A; SPI1 Controller In Target Out Port Map B; LPTMR0 Output 32 Bits or Lower 16 Bits Port Map C; ADC Input 0/Comparator 0/1 Negative Input; When used as VREF for the ADC, requires 1µF bypass to VSSA and AIN0 is not available.
2	P0.14	P0.14	PT0A	—	—	—	—	Pulse Train 0 Port Map A
8	P0.15	P0.15	PT1A	CAN0B_RX	TMR2C_IA	TMR0D_IA	—	Pulse Train 1 Port Map A; CAN Receive Port Map B; TMR2 Input 32 Bits or Lower 16 Bits Port Map C; TMR0 Input 32 Bits or Lower 16 Bits Port Map D
9	P0.16	P0.16	PT2A	CAN0B_TX	TMR2C_OA	TMR0D_OA	—	Pulse Train 2 Port Map A; CAN Transmit Port Map B; TMR2 Output 32 Bits or Lower 16 Bits Port Map C; TMR0 Output 32 Bits or Lower 16 Bits Port Map D
16	P0.17	P0.17	SPI1A_SCK	—	ADC_TRIG_C	UART0D_CTS	—	SPI1 Serial Clock Port Map A; ADC Trigger Input Port Map C; UART0 CTS Port Map D
17	P0.18	P0.18	SPI1A_TS0	—	—	UART0D_RTS	—	SPI1 Target Select 0 Port Map A; UART0 RTS Port Map D
19	P0.19	P0.19	UART0A_RTS	—	TMR1C_IA	—	—	UART0 RTS Port Map A; TMR1 Input 32 Bits or Lower 16 Bits Port Map C
20	P0.20	P0.20	UART0A_CTS	—	TMR1C_OA	—	—	UART0 CTS Port Map A; TMR1 Output 32 Bits or Lower 16 Bits Port Map C

## Detailed Description

The device features five powerful and flexible power modes, and can operate from a single-supply battery or a dual-supply provided by a PMIC. The I<sup>2</sup>C ports support Standard-mode, Fast-mode, Fast-mode Plus, and High-speed modes, operating up to 3400kbps. The SPI ports can run up to 50MHz in both controller and peripheral mode. The 12-bit SAR ADC provides an integrated reference generator and a single-ended input multiplexer. The integrated CAN 2.0B interface is compliant with Bosch CAN 2.0B specification (2.0B Active) according to ISO 11898-1. Three general-purpose 32-bit timers, one low-power 32-bit timer, one windowed watchdog timer, and a real-time clock (RTC) are also provided. An I<sup>2</sup>S interface provides digital audio streaming to a codec. An Elliptic Curve Digital Signature Algorithm (ECDSA)-based cryptographic secure bootloader is available in ROM.

### Arm Cortex-M4 Processor with FPU Engine

The Arm Cortex-M4 with FPU processor combines high-efficiency signal processing functionality with low power, low cost, and ease of use.

The Arm Cortex-M4 with FPU DSP supports single instruction, multiple data (SIMD) path DSP extensions, providing:

- Four parallel 8-bit add/sub
- Floating point single precision
- Two parallel 16-bit add/sub
- Two parallel MACs
- 32- or 64-bit accumulate
- Signed, unsigned, data with or without saturation

## Memory

### Internal Flash Memory

The 256KB internal flash memory provides nonvolatile storage of program and data memory.

### Internal SRAM

The internal 80KB SRAM provides low-power retention of application information in all power modes except STORAGE. The SRAM can be divided into granular banks that create a flexible SRAM retention architecture. This data retention feature is optional and is configurable. This granularity allows the application to minimize its power consumption by only retaining the essential data.

## Clocking Scheme

The internal primary oscillator (IPO) operates at a nominal frequency of 100MHz. Optionally, the software can select one of five other oscillators depending upon power needs:

- 80kHz oscillator (INRO)
- 32.768kHz oscillator (external crystal required) (ERTCO)
- 7.3728MHz oscillator (IBRO)
- 16MHz–32MHz oscillator (external crystal required) (ERFO)
- External square-wave clocks up to 50MHz

This IPO is the primary clock source for digital logic and peripherals. An external 32.768kHz timebase is required when using the RTC. A separate external square-wave clock can be used as a source for LPTMR0 in the always-ON domain.

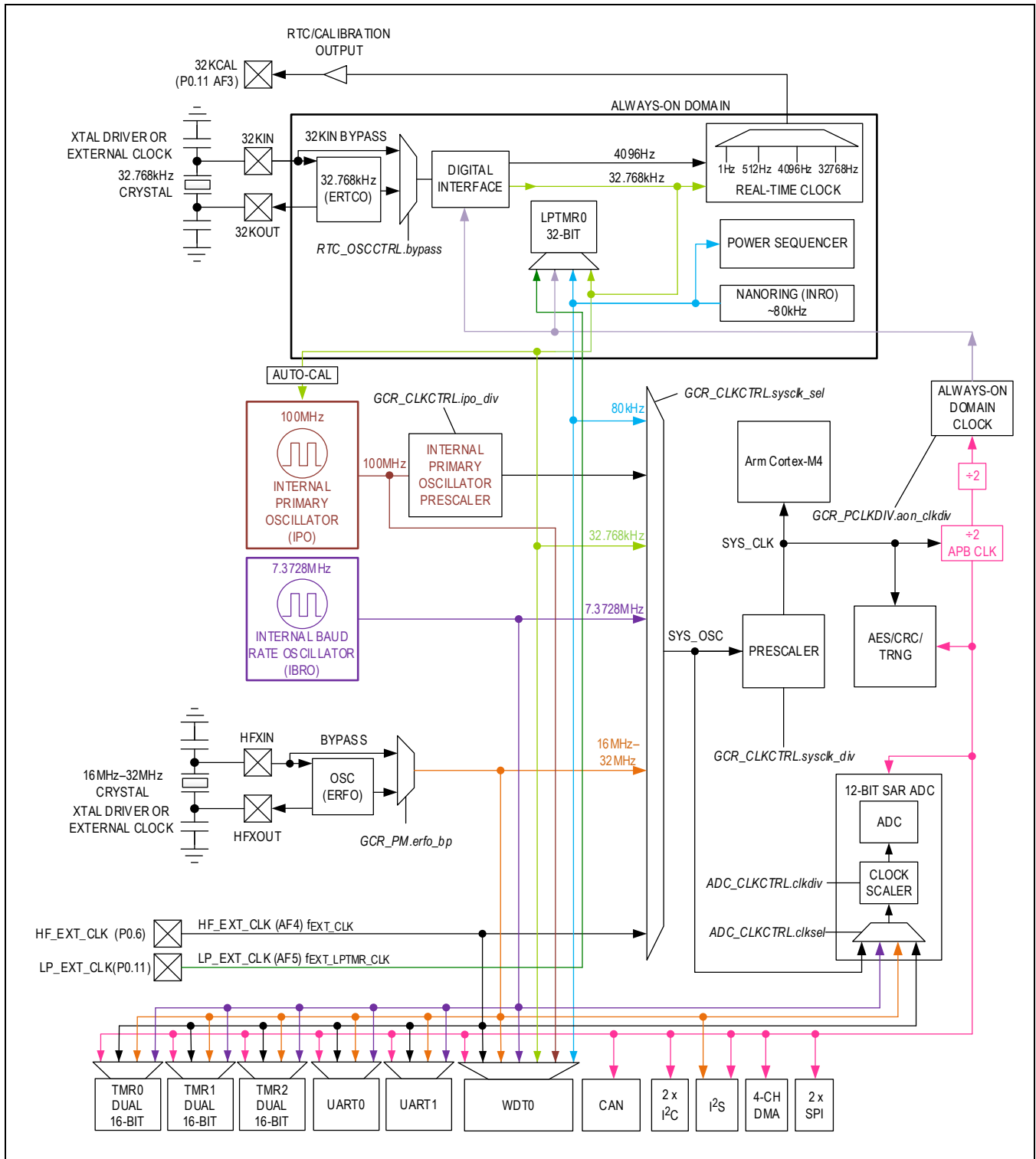


Figure 6. Clocking Scheme Diagram

## General-Purpose I/O and Special Function Pins

Most general-purpose I/O (GPIO) pins share both a firmware-controlled I/O function and one or more special function signals associated with peripheral modules. Software can individually enable pins for GPIO or peripheral special function use. Configuring a pin as a special function supersedes its use as a software-controlled I/O. Multiplexing between peripheral and GPIO functions is usually static but can also be done dynamically by software. The electrical characteristics of a GPIO pin are identical whether the pin is configured as an I/O or special function, except where explicitly noted in the [Electrical Characteristics](#) tables.

In GPIO mode, each pin of a port has an interrupt function that can be independently enabled by software and configured as a level- or edge-sensitive interrupt. All GPIOs share the same interrupt vector. Some packages do not have all of the GPIOs available.

When configured as GPIOs, the following features are provided. These features can be independently enabled or disabled on a per-pin basis.

- Configurable as input, output, bidirectional, or high-impedance
- Optional internal pull-up resistor or internal pull-down resistor when configured as input
- Exit from low-power modes on rising or falling edge
- Selectable standard- or high-drive modes

The MAX32662 provides up to 21 GPIOs for the 32-pin TQFN.

## Standard DMA Controller

The standard direct memory access (DMA) controller provides a means to offload the CPU for memory/peripheral data transfer leading to a more power-efficient system. It allows automatic one-way data transfer between two entities. These entities can be either memories or peripherals. The transfers are done without using CPU resources. The DMA peripheral supports the following features:

- 4 channel
- Peripheral to SRAM transfer
- SRAM to peripheral transfer
- SRAM to SRAM transfer
- Event support
- All DMA transactions consist of an AHB burst read into the DMA FIFO followed immediately by an AHB burst write from the FIFO.

## Power Management

### Power Management Unit

The power management unit (PMU) provides the optimal mix of high-performance and low-power consumption. It exercises intelligent, precise control of power distribution to the CPU and peripheral circuitry.

The PMU provides the following features:

- User-configurable system clock
- Automatic enabling and disabling of crystal oscillators based on power mode
- Multiple clock domains
- Unused peripherals can be selectively powered down
- Fast wake up of powered-down peripherals when activity detected

## Operating Modes

### ACTIVE

In this mode, the CPU executes software, and all digital and analog peripherals are available on demand. Dynamic clocking disables local clocks in peripherals that are not in use. This mode corresponds to the Arm Cortex-M4 processor with FPU ACTIVE mode.

## SLEEP

This mode allows for lower power consumption operations than ACTIVE mode. The CPU is asleep, peripherals are on, and the standard DMA block is available. The GPIO or any active peripheral can be configured to interrupt and cause a transition to ACTIVE mode. This mode corresponds to the Arm Cortex-M4 processor's SLEEP mode.

## DEEPSLEEP

In this mode, CPU and critical peripheral configuration settings and all volatile memory is preserved.

The device status is as follows:

- The CPU is powered down. System state and all SRAM is retained.
- The GPIO pins retain their state.
- The transition from DEEPSLEEP to ACTIVE mode is faster than the transition from BACKUP mode because system initialization is not required.
- The system oscillators are all disabled to provide additional power savings over SLEEP mode.
- The LPTMR0 can be active and is an optional wake-up source.

This mode corresponds to the Arm Cortex-M4 processor's DEEPSLEEP mode.

## BACKUP

This mode places the CPU in a static, low-power state. The BACKUP mode supports the same wake-up sources as DEEPSLEEP mode.

The device status is as follows:

- CPU is powered down.
- SRAM retention as per [Table 1](#).
- LPTMR0 can be active and is an optional wake-up source.

**Table 1. BACKUP Mode SRAM Retention**

SRAM BLOCK	SRAM SIZE	RETAINED SRAM
SYSRAM0	20KB	17KB
SYSRAM1	20KB	18KB
SYSRAM2	20KB	19KB
SYSRAM3	20KB	20KB

**Note:** The boot ROM uses certain ranges of system RAM during a system reset, watchdog timer reset, an external reset, and an exit from BACKUP. The device uses this RAM to perform system checks. As a result, not all of each RAM can be retained during an exit from BACKUP. Refer to the [MAX32662 User Guide](#) for additional details.

## STORAGE

The device status is as follows:

- The CPU is powered off.
- All peripherals are powered off.
- Wake up from GPIO interrupt.
- The RTC can be enabled by software before entering STORAGE mode.
- No SRAM retention.



## Wake-Up Sources

The wake-up sources from the SLEEP, DEEPSLEEP, BACKUP, and STORAGE modes are summarized in [Table 2](#).

**Table 2. Wake-Up Sources**

OPERATING MODE	WAKE-UP SOURCE
SLEEP	Interrupts (GPIO or any active peripheral), RSTN assertion
DEEPSLEEP	Interrupts (RTC, GPIO), RSTN assertion, LPTMR0
BACKUP	Interrupts (RTC, GPIO), RSTN assertion, LPTMR0
STORAGE	Interrupts (RTC, GPIO), RSTN assertion

## Real-Time Clock (RTC)

An RTC keeps the time of day in absolute seconds. The 32-bit seconds register can count up to approximately 136 years and be translated to calendar format by application software.

The RTC provides a time-of-day alarm programmed by software to any future value between 1 second and 12 days. When configured for long intervals, the time-of-day alarm can be used as a power-saving timer, allowing the device to remain in an extremely low-power mode but still awaken periodically to perform assigned tasks. Software can program a second independent 32-bit 1/4096 sub-second alarm between 244 $\mu$ s and 12 days. Both can be configured as recurring alarms. When enabled, either alarm can cause an interrupt or wake the device from most low-power modes.

The time base is generated by a 32.768kHz crystal or an external clock source that must meet the electrical/timing requirements in the [Electrical Characteristics](#) table.

An RTC calibration feature allows the software to compensate for minor variations in the RTC oscillator, crystal, temperature, and board layout. Enabling the 32KCAL alternate function outputs a timing signal derived from the RTC. External hardware can measure the frequency and adjust the RTC frequency in increments of  $\pm 127$ ppm with a 1ppm resolution. Under most circumstances, the oscillator does not require any calibration.

## Windowed Watchdog Timer (WDT)

Microcontrollers are often used in harsh environments where electrical noise and electromagnetic interference (EMI) are abundant. Without proper safeguards, these hazards can disturb device operation and corrupt program execution. One of the most effective countermeasures is the WDT, which detects runaway code or system unresponsiveness.

The WDT is a 32-bit, free-running counter with a configurable prescaler. When enabled, the WDT must be periodically reset by the application software. Failure to reset the WDT within the user-configurable timeout period indicates that the application software is not operating correctly and results in a WDT timeout. A WDT timeout can trigger an interrupt, system reset, or both. Either response forces the instruction pointer to a known good location before resuming instruction execution. The windowed timeout period feature provides more detailed monitoring of system operation, requiring the WDT to be reset within a specific time window.

The WDT supports multiple clock options:

- IPO
- ERFO (external crystal required)
- IBRO
- INRO
- ERTCO (external crystal required)
- External clock input
- Peripheral clock (PCLK)

### 32-Bit Timer/Counter/PWM

General-purpose, 32-bit timers provide timing, capture/compare, or generate pulse-width modulated (PWM) signals with minimal software interaction.

The timer provides the following features:

- 32-bit up/down auto-reload
- Programmable prescaler
- PWM output generation
- Capture, compare, and capture/compare capability
- External pin multiplexed with GPIO for timer input, clock gating, or capture
- Timer output pin
- TMR0-TMR3 configurable as 2 × 16-bit general-purpose timers
- Timer interrupt

I/O functionality is supported for all of the timers. Note that the function of a port can be multiplexed with other functions on the GPIO pins, so it might not be possible to use all the ports depending on the device configuration. See [Table 3](#) for individual timer features.

**Table 3. Timer Configuration Options**

INSTANCE	32-BIT	DUAL 16-BIT	MODE	CLOCK SOURCE						
				PCLK	IBRO	ERFO	INRO	ERTCO	HF_EXT_CLK	LP_EXT_CLK
TMR0	Yes	Yes	ACTIVE	Yes	Yes	Yes	No	No	Yes	No
TMR1	Yes	Yes	ACTIVE	Yes	Yes	Yes	No	No	Yes	No
TMR2	Yes	Yes	ACTIVE	Yes	Yes	Yes	No	No	Yes	No
LPTMR0	Yes	No	ACTIVE/SLEEP/ DEEPSLEEP/ BACKUP	Yes	No	No	Yes	Yes	No	Yes

### Serial Peripherals

#### Controller Area Network (CAN) 2.0B

The integrated CAN 2.0B interface is compliant with the Bosch CAN 2.0B (active) specification according to ISO 11898-1.

The following are the key features of the interface:

- Compliant with ISO 11898-1:2015 specification
- Supports up to 8-byte data frame
- Selectable ID type
  - 11-bit standard ID
  - 11-bit standard ID + 18-bit extended ID
- Selectable frame type.
  - Data frame (remote transmission request (RTR) = 0)
  - Remote frame (RTR = 1)
- Hardware message filtering (dual/single filters)
- DMA support for transmit and receive
- 128-byte transmit buffer and 256-byte receive buffer
- Overload frame is generated on a FIFO overflow
- Protocol exception event detection
- Normal and Listen Only modes supported
- Transmitter delay compensation up to 3 data bits long
- Single-shot transmission
- Readable error counters

- Last error code
- Sleep mode and wake-up unit

### I<sup>2</sup>C Interface

The I<sup>2</sup>C interface is a bidirectional, two-wire serial bus that provides a medium-speed communications network. It can operate as a one-to-one, one-to-many, or many-to-many communications medium. These engines support Standard-mode, Fast-mode, Fast-mode Plus, and High-speed mode I<sup>2</sup>C speeds.

The I<sup>2</sup>C interface provides the following features:

- Controller or Target mode operation
  - Supports up to four different addresses in Target mode
- Supports standard 7-bit addressing or 10-bit addressing
- RESTART condition
- Interactive receive mode
- Transmit FIFO preloading
- Support for clock stretching to allow slower target devices to operate on higher speed busses
- Multiple transfer rates
  - Standard-mode: 100kbps
  - Fast-mode: 400kbps
  - Fast-mode Plus: 1000kbps
  - High-speed mode: 3400kbps
- Internal filter to reject noise spikes
- 8-byte receive FIFO
- 8-byte transmit FIFO

### Serial Peripheral Interface (SPI)

The SPI is a highly configurable, flexible, and efficient synchronous interface between multiple SPI devices on a single bus. The bus uses a single clock signal and multiple data signals and one or more target select lines to address only the intended target device. The SPI operates independently and requires minimal processor overhead.

The provided SPI peripherals can operate in either target or controller mode and provide the following features:

- SPI modes 0, 1, 2, and 3 for single-bit communication
- 3- or 4-wire mode for single-bit target device communication
- Full-duplex operation in single-bit, 4-wire mode
- Multicontroller mode fault detection
- Programmable interface timing
- Programmable SCK frequency and duty cycle
- 32-byte transmit FIFO
- 32-byte receive FIFO
- Target select assertion and deassertion timing relative to leading/trailing SCK edge

See [Table 4](#) for configuration options.

**Table 4. SPI Configuration Options**

INSTANCE	INTERFACE FORMAT	TARGET SELECT LINES	MAXIMUM FREQUENCY (CONTROLLER MODE) (MHz)	MAXIMUM FREQUENCY (TARGET MODE) (MHz)
SPI0	3 wire, 4 wire	1	50	50
SPI1	3 wire, 4 wire	1	50	50

### I<sup>2</sup>S Interface

The I<sup>2</sup>S interface is a bidirectional, 4-wire serial bus that provides serial communications for codecs and audio amplifiers compliant with the I<sup>2</sup>S Bus Specification, June 5, 1996.

The I<sup>2</sup>S interface provides the following features:

- Controller and Target mode operation
- Support for four channels
- 8-, 16-, 24-, and 32-bit frames
- Receive and transmit DMA support
- Wake-up on FIFO status (full/empty/threshold)
- Pulse density modulation support for the receive channel
- Word select polarity control
- First-bit position selection
- Interrupts generated for FIFO status
- 32-byte receive FIFO
- 32-byte transmit FIFO

### Universal Asynchronous Receiver Transmitter (UART) Interface

The UART interface supports full-duplex asynchronous communication with optional hardware flow control (HFC) modes to prevent data overruns. If HFC mode is enabled on a given port, the system uses two extra pins to implement the industry-standard request-to-send (RTS) and clear-to-send (CTS) flow control signaling. Each UART is individually programmable.

- 2-wire interface or 4-wire interface with flow control
- 8-byte receive FIFO
- 8-byte transmit FIFO
- Full-duplex operation for asynchronous data transfers
- Interrupts available for:
  - Frame error
  - Parity error
  - CTS
  - Receive FIFO overrun
  - FIFO full/partially full conditions
- Automatic parity and frame error detection
- Independent baud-rate generator
- Programmable 9th-bit parity support
- Multidrop support
- Start/stop bit support
- Hardware flow control using RTS/CTS
- Two DMA channels can be connected (read and write FIFOs)
- Programmable word size (5 bits to 8 bits)

See [Table 5](#) for configuration options.

**Table 5. UART Configuration Options**

INSTANCE	PACKAGE		MODE	CLOCK SOURCES					
	20 WLP	32 TQFN		PCLK	IBRO	ERFO	INRO	ERTCO	HF_EXT_CLK
UART0	4 wire	4 wire	ACTIVE	Yes	Yes	Yes	No	No	Yes
UART1	2 wire	4 wire	ACTIVE	Yes	Yes	Yes	No	No	Yes

### Analog-to-Digital Converter (ADC)

The 12-bit SAR ADC provides an integrated reference generator and a single-ended input multiplexer. The multiplexer selects an input channel from one of the four external analog alternate function input signals (AIN0–AIN3) and the internal power supply inputs.

The reference for the ADC can be:

- External alternate function  $V_{REF}$  input shared with AIN0, AIN\_C0\_N1, and AIN\_C1\_N1.
- Internal 1.25V
- Internal 2.048V

The ADC measures the following voltages:

- AIN[3:0] up to  $V_{DDIO}$
- $V_{DDIO} \div 4$
- $V_{CORE}$
- $V_{DDA} \div 2$
- $V_{SSA}$

### Security

#### AES

The dedicated hardware-based AES engine supports the following algorithms:

- AES-128
- AES-192
- AES-256

The AES keys are generated by the TRNG and the application software can store the keys in secure NV memory.

#### True Random Number Generator (TRNG)

Random numbers are a vital part of a secure application. They are used as cryptographic seeds or to create strong encryption keys to ensure data privacy. Software can use random numbers to trigger asynchronous events that cause nondeterministic behavior. This helps thwart replay or key search attacks.

The TRNG is continuously fed by a physically-unpredictable, high-entropy source. It generates a 128-bit true random number in 128 system clock cycles.

The TRNG can support the system-level validation of many security standards.

#### CRC Module

A cyclic redundancy check (CRC) hardware module provides fast calculations and data integrity checks by application software. The CRC polynomial is programmable to support custom CRC algorithms as well as the common algorithms shown in [Table 6](#).

**Table 6. Common CRC Polynomials**

ALGORITHM	POLYNOMIAL EXPRESSION
CRC-32-ETHERNET	$x^{32} + x^{26} + x^{23} + x^{22} + x^{16} + x^{12} + x^{11} + x^{10} + x^8 + x^7 + x^5 + x^4 + x^2 + x^1 + x^0$
CRC-CCITT	$x^{16} + x^{12} + x^5 + x^0$
CRC-16	$x^{16} + x^{15} + x^2 + x^0$
USB DATA	$x^{16} + x^{15} + x^2 + x^0$
PARITY	$x^1 + x^0$

## Root of Trust

On devices that support SCPBL, the root of trust starts with trusted software and the microcontroller's complement of security features. Communications between a host and the device must be secure and authenticated, and program integrity must be verified each time before execution to ensure the device's trustworthiness. The device's root of trust is based on a secret Analog Devices root verification key and a signed customer verification key (CVK). Customers submit their public CVK, which is then signed, and a certificate is sent back to the customer. This process is quick and required only once, before the software is released for the first time, and is unnecessary during the software development. A customer can then load their own key and download their signed binary executable code.

## Secure Communications Protocol Bootloader (SCPBL)

On devices that support SCPBL, communication between a host system and the device uses a system of ECDSA-256 digitally signed packets. This guarantees the integrity and authenticity of all communication before executing configuration commands and the loading or verification of program memory. One or more serial interfaces are available for communication. This also enables the assembly and programming of the customer's final product by third-party assembly houses without the required cost and complexity of ensuring that the assembly house implements and maintains a secure production facility. It also allows for in-field software upgrades to deployed products, thus eliminating the costly need to return a product to the manufacturer for any software changes.

The serial interfaces available for SCPBL communication are shown in [Table 7](#). Following any reset or exit from certain low-power modes, the device tests the assigned stimulus pin and, if active, begins an SCPBL session. The stimulus pin can be reassigned once an SCPBL session begins. The host can disable the bootloader interface before deployment to prevent any changes to program memory.

See the [Ordering Information](#) table for availability.

## Secure Boot

On devices that support SCPBL, following every reset, the device performs a secure boot to confirm the root of trust has not been compromised. The secure boot verifies the digital signature of the program memory to confirm it has not been modified or corrupted, ensuring the trustworthiness of the application software. Failure to verify the digital signature transitions the device to safe mode, which prevents execution of the customer code. If not previously deactivated, the bootloader can be reactivated and a new, trusted program memory loaded.

## Debug and Development Interface

The serial wire debug (SWD) interface is used for code loading and in-circuit emulator (ICE) debug activities.

## Additional Documentation

Designers must have the following documents to use all the features of this device:

- This data sheet, which contains electrical/timing specifications, package information, and pin descriptions
- The corresponding revision-specific errata sheet
- The corresponding [MAX32662 User Guide](#), which contains detailed information and programming guidelines for core features and peripherals

## Applications Information

### Bootloader Activation

The SCPBL can use the interfaces shown in [Table 7](#).

**Table 7. Bootloader Activation Summary**

PART NUMBER	BOOTLOADER INTERFACE	DEFAULT STIMULUS PIN
	UART0	
All versions	UART0_RX UART0_TX RSTN	P0.6 (active low)

On devices that support SCPBL, the SCPBL is activated following any reset or exiting certain low-power modes if the assigned stimulus pin is asserted. The design must ensure that the desired bootloader interface and stimulus pin is accessible by the host or the SCPBL cannot be activated. A different stimulus pin may be assigned once an SCPBL session has been started. The stimulus pin must be driven externally to a known state at all times.

The RSTN signal must also be accessible by the host for initial synchronization with the SCPBL.

### **Bypass Capacitors**

The proper use of bypass capacitors reduces noise generated by the IC into the ground plane. The [Pin Descriptions](#) indicate which pins should be connected to bypass capacitors and the appropriate ground plane.

It is recommended that one instance of a bypass capacitor should be connected to each pin/ball of the IC package. For example, if the [Pin Descriptions](#) show four device pins associated with voltage supply A, a separate capacitor should be connected to each pin for a total of four capacitors.

Place capacitors as close as possible to their corresponding device pins. When more than one value of capacitor is recommended per pin, the capacitors should be placed in parallel starting with the lowest value capacitor closest to the pin.

**Typical Fixed Current Consumption Temperature Variance**

Single-Supply ACTIVE Mode  $f_{\text{sys\_osc}} = \text{IPO}$

**Table 8. Single-Supply Operation Fixed  $V_{\text{DDIO}}$  Current Consumption ACTIVE Mode  
 $f_{\text{sys\_osc}} = \text{IPO}$**

PARAMETER	SYMBOL	COMMON CONDITIONS	CONDITIONS	TYPICAL					UNITS
				-40°C	25°C	55°C	85°C	105°C	
$V_{\text{DDIO}}$ Current, ACTIVE Mode	$I_{\text{DD\_FACTS}}$	Fixed, IPO enabled, total current into $V_{\text{DDIO}}$ and $V_{\text{DDA}}$ pins, $V_{\text{DDIO}} = 3.3\text{V}$ , CPU in ACTIVE mode 0MHz execution, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPC TRL.ovr = 0b10, internal regulator set to 1.1V	595	685	835	1155	1310	$\mu\text{A}$
			PWRSEQ_LPC TRL.ovr = 0b01, internal regulator set to 1.0V	505	585	705	940	1100	$\mu\text{A}$
			PWRSEQ_LPC TRL.ovr = 0b00, internal regulator set to 0.9V	440	510	610	805	945	$\mu\text{A}$
		Fixed, IPO enabled, total current into $V_{\text{DDIO}}$ and $V_{\text{DDA}}$ pins, $V_{\text{DDIO}} = 1.8\text{V}$ , CPU in ACTIVE mode 0MHz execution, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPC TRL.ovr = 0b10, internal regulator set to 1.1V	575	665	810	1090	1285	$\mu\text{A}$
			PWRSEQ_LPC TRL.ovr = 0b01, internal regulator set to 1.0V	490	565	685	915	1075	$\mu\text{A}$
			PWRSEQ_LPC TRL.ovr = 0b00, internal regulator set to 0.9V	425	490	590	780	920	$\mu\text{A}$



Single-Supply SLEEP Mode  $f_{\text{SYS\_OSC}} = \text{IPO}$

**Table 9. Single-Supply Operation Fixed  $V_{\text{DDIO}}$  Current Consumption SLEEP Mode  
 $f_{\text{SYS\_OSC}} = \text{IPO}$**

PARAMETER	SYMBOL	COMMON CONDITIONS	CONDITIONS	TYPICAL					UNITS
				-40°C	25°C	55°C	85°C	105°C	
$V_{\text{DDIO}}$ Current, SLEEP Mode	$I_{\text{DDIO\_FSLPS}}$	Fixed, IPO enabled, total current into $V_{\text{DDIO}}$ and $V_{\text{DDA}}$ pins, $V_{\text{DDIO}} = 3.3\text{V}$ , CPU in SLEEP mode, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPCT RL.ovr = 0b10, internal regulator set to 1.1V	595	685	835	1155	1310	$\mu\text{A}$
			PWRSEQ_LPCT RL.ovr = 0b01, internal regulator set to 1.0V	505	585	705	940	1100	$\mu\text{A}$
			PWRSEQ_LPCT RL.ovr = 0b00, internal regulator set to 0.9V	440	510	610	805	945	$\mu\text{A}$
		Fixed, IPO enabled, total current into $V_{\text{DDIO}}$ and $V_{\text{DDA}}$ pins, $V_{\text{DDIO}} = 1.8\text{V}$ , CPU in SLEEP mode, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPCT RL.ovr = 0b10, internal regulator set to 1.1V	575	665	810	1090	1285	$\mu\text{A}$
			PWRSEQ_LPCT RL.ovr = 0b01, internal regulator set to 1.0V	490	565	685	915	1075	$\mu\text{A}$
			PWRSEQ_LPCT RL.ovr = 0b00, internal regulator set to 0.9V	425	490	590	780	920	$\mu\text{A}$

Single-Supply ACTIVE Mode  $f_{\text{sys\_osc}} = \text{IBRO}$

**Table 10. Single-Supply Operation Fixed  $V_{\text{DDIO}}$  Current Consumption ACTIVE Mode  
 $f_{\text{sys\_osc}} = \text{IBRO}$**

PARAMETER	SYMBOL	COMMON CONDITIONS	CONDITIONS	TYPICAL					UNITS
				-40°C	25°C	55°C	85°C	105°C	
$V_{\text{DDIO}}$ Current, ACTIVE Mode	IDDIO_FACTS	Fixed, IBRO enabled, total current into $V_{\text{DDIO}}$ and $V_{\text{DDA}}$ pins, $V_{\text{DDIO}} =$ 3.3V, CPU in ACTIVE mode 0MHz execution, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPC TRL.ovr = 0b10, internal regulator set to 1.1V	210	280	410	675	865	$\mu\text{A}$
			PWRSEQ_LPC TRL.ovr = 0b01, internal regulator set to 1.0V	200	255	360	575	735	$\mu\text{A}$
			PWRSEQ_LPC TRL.ovr = 0b00, internal regulator set to 0.9V	190	230	320	500	635	$\mu\text{A}$
		Fixed, IBRO enabled, total current into $V_{\text{DDIO}}$ and $V_{\text{DDA}}$ pins, $V_{\text{DDIO}} =$ 1.8V, CPU in ACTIVE mode 0MHz execution, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPC TRL.ovr = 0b10, internal regulator set to 1.1V	185	255	385	645	835	$\mu\text{A}$
			PWRSEQ_LPC TRL.ovr = 0b01, internal regulator set to 1.0V	175	230	335	550	705	$\mu\text{A}$
			PWRSEQ_LPC TRL.ovr = 0b00, internal regulator set to 0.9V	170	210	295	470	605	$\mu\text{A}$

Single-Supply SLEEP Mode  $f_{\text{SYS\_OSC}} = \text{IBRO}$

**Table 11. Single-Supply Operation Fixed  $V_{\text{DDIO}}$  Current Consumption SLEEP Mode  
 $f_{\text{SYS\_OSC}} = \text{IBRO}$**

PARAMETER	SYMBOL	COMMON CONDITIONS	CONDITIONS	TYPICAL					UNITS
				-40°C	25°C	55°C	85°C	105°C	
$V_{\text{DDIO}}$ Current, SLEEP Mode	$I_{\text{DDIO\_FSLPS}}$	Fixed, IBRO enabled, total current into $V_{\text{DDIO}}$ and $V_{\text{DDA}}$ pins, $V_{\text{DDIO}} =$ 3.3V, CPU in SLEEP mode, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPC TRL.ovr = 0b10, internal regulator set to 1.1V	210	280	410	675	865	$\mu\text{A}$
			PWRSEQ_LPC TRL.ovr = 0b01, internal regulator set to 1.0V	200	255	360	575	735	$\mu\text{A}$
			PWRSEQ_LPC TRL.ovr = 0b00, internal regulator set to 0.9V	190	230	320	500	635	$\mu\text{A}$
		Fixed, IBRO enabled, total current into $V_{\text{DDIO}}$ and $V_{\text{DDA}}$ pins, $V_{\text{DDIO}} =$ 1.8V, CPU in SLEEP mode, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPC TRL.ovr = 0b10, internal regulator set to 1.1V	185	255	385	645	835	$\mu\text{A}$
			PWRSEQ_LPC TRL.ovr = 0b01, internal regulator set to 1.0V	175	230	335	550	705	$\mu\text{A}$
			PWRSEQ_LPC TRL.ovr = 0b00, internal regulator set to 0.9V	170	210	295	470	605	$\mu\text{A}$

Single-Supply DEEPSLEEP Mode

**Table 12. Single-Supply Operation Fixed  $V_{DDIO}$  Current Consumption DEEPSLEEP Mode**

PARAMETER	SYMBOL	COMMON CONDITIONS	CONDITIONS	TYPICAL					UNITS
				-40°C	25°C	55°C	85°C	105°C	
V <sub>DDIO</sub> Fixed Current, DEEPSLEEP Mode	I <sub>DDIO_FDSLPS</sub>	Standby state with full data retention and 80KB SRAM retained	V <sub>DDIO</sub> = 3.3V. PWRSEQ_LPCTRL. fastwken = 0, PWRSEQ_LPCTRL. bg_dis = 0.	1.6	3.6	9.6	26	40	μA
			V <sub>DDIO</sub> = 1.8V. PWRSEQ_LPCTRL. fastwken = 0, PWRSEQ_LPCTRL. bg_dis = 0.	1.4	3.3	9.2	25	39	μA

Single-Supply BACKUP Mode

**Table 13. Single-Supply Operation Fixed  $V_{DDIO}$  Current Consumption BACKUP Mode**

PARAMETER	SYMBOL	COMMON CONDITIONS	CONDITIONS	TYPICAL					UNITS
				-40°C	25°C	55°C	85°C	105°C	
V <sub>DDIO</sub> Fixed Current, BACKUP Mode	I <sub>DDIO_FBKUS</sub>	V <sub>DDIO</sub> = 3.3V, RTC disabled	0KB SRAM retained, retention regulator disabled	0.35	0.45	0.7	1.3	1.9	μA
			20KB SRAM retained, retention regulator disabled	0.77	1.25	2.35	5.4	8.2	μA
			40KB SRAM retained, retention regulator disabled	0.9	1.6	3.45	8.5	13	μA
			60KB SRAM retained, retention regulator disabled	1.1	2	4.7	11.5	18	μA
			80KB SRAM retained, retention regulator disabled	1.2	2.4	5.8	14.6	23	μA
		V <sub>DDIO</sub> = 1.8V, RTC disabled	0KB SRAM retained, retention regulator disabled	0.2	0.23	0.35	0.8	1.2	μA
			20KB SRAM retained, retention regulator disabled	0.6	1	2	4.8	7.5	μA
			40KB SRAM retained, retention regulator disabled	0.8	1.4	3.1	7.8	12.1	μA
			60KB SRAM retained, retention regulator disabled	0.9	1.8	4.3	11	17	μA
			80KB SRAM retained, retention regulator disabled	1.1	2.15	5.4	14	22	μA

Single-Supply STORAGE Mode

**Table 14. Single-Supply Operation Fixed  $V_{DDIO}$  Current Consumption STORAGE Mode**

PARAMETER	SYMBOL	CONDITIONS	TYPICAL					UNITS
			-40°C	25°C	55°C	85°C	105°C	
V <sub>DDIO</sub> Fixed Current, STORAGE Mode	I <sub>DDIO_FSTOS</sub>	V <sub>DDIO</sub> = 3.3V	0.12	0.23	0.5	1.1	1.7	μA
		V <sub>DDIO</sub> = 1.8V	0.02	0.06	0.2	0.6	1.1	μA

Dual-Supply ACTIVE Mode  $f_{\text{SYS\_OSC}} = \text{IPO}$

**Table 15. Dual-Supply Operation Fixed  $V_{\text{CORE}}$  Current Consumption ACTIVE Mode  
 $f_{\text{SYS\_OSC}} = \text{IPO}$**

PARAMETER	SYMBOL	COMMON CONDITIONS	CONDITIONS	TYPICAL					UNITS
				-40°C	25°C	55°C	85°C	105°C	
$V_{\text{CORE}}$ Current, ACTIVE Mode	$I_{\text{CORE\_FACTD}}$	Fixed, IPO enabled, total current into $V_{\text{CORE}}$ pin, CPU in ACTIVE mode 0MHz operation, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, $V_{\text{CORE}} = 1.1\text{V}$	190	250	380	640	830	$\mu\text{A}$
			PWRSEQ_LPCTR L.ovr = 0b01, $V_{\text{CORE}} = 1.0\text{V}$	100	145	250	470	620	$\mu\text{A}$
			PWRSEQ_LPCTR L.ovr = 0b00, $V_{\text{CORE}} = 0.9\text{V}$	40	70	150	310	430	$\mu\text{A}$

**Table 16. Dual-Supply Operation Fixed  $V_{\text{DDIO}}$  Current Consumption ACTIVE Mode  
 $f_{\text{SYS\_OSC}} = \text{IPO}$**

PARAMETER	SYMBOL	COMMON CONDITIONS	CONDITIONS	TYPICAL					UNITS
				-40°C	25°C	55°C	85°C	105°C	
$V_{\text{DDIO}}$ Current, ACTIVE Mode	$I_{\text{DDIO\_FACTD}}$	Fixed, IPO enabled, total current into $V_{\text{DDIO}}$ and $V_{\text{DDA}}$ pins, $V_{\text{DDIO}} = 3.3\text{V}$ , CPU in ACTIVE mode 0MHz operation, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPCTRL.ovr = 0b10, internal regulator set to 1.1V	355	385	400	420	430	$\mu\text{A}$
			PWRSEQ_LPCTRL.ovr = 0b01, internal regulator set to 1.0V	355	385	400	420	430	$\mu\text{A}$
			PWRSEQ_LPCTRL.ovr = 0b00, internal regulator set to 0.9V	355	385	400	420	430	$\mu\text{A}$
		Fixed, IPO enabled, total current into $V_{\text{DDIO}}$ and $V_{\text{DDA}}$ pins, $V_{\text{DDIO}} = 1.8\text{V}$ , CPU in ACTIVE mode 0MHz operation, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPCTRL.ovr = 0b10, internal regulator set to 1.1V	340	370	385	400	410	$\mu\text{A}$
			PWRSEQ_LPCTRL.ovr = 0b01, internal regulator set to 1.0V	340	370	385	400	410	$\mu\text{A}$
			PWRSEQ_LPCTRL.ovr = 0b00, internal regulator set to 0.9V	340	370	385	400	410	$\mu\text{A}$

Dual-Supply SLEEP Mode  $f_{\text{sys\_osc}} = \text{IPO}$

**Table 17. Dual-Supply Operation Fixed  $V_{\text{CORE}}$  Current Consumption SLEEP Mode  
 $f_{\text{sys\_osc}} = \text{IPO}$**

PARAMETER	SYMBOL	COMMON CONDITIONS	CONDITIONS	TYPICAL					UNITS
				-40°C	25°C	55°C	85°C	105°C	
$V_{\text{CORE}}$ Current, SLEEP Mode	$I_{\text{CORE\_FSLPD}}$	Fixed, IPO enabled, total current into $V_{\text{CORE}}$ pin, CPU in SLEEP mode, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPCTRL. ovr = 0b10, $V_{\text{CORE}} = 1.1\text{V}$	190	250	380	640	830	$\mu\text{A}$
			PWRSEQ_LPCTRL. ovr = 0b01, $V_{\text{CORE}} = 1.0\text{V}$	100	145	250	465	620	$\mu\text{A}$
			PWRSEQ_LPCTRL. ovr = 0b00, $V_{\text{CORE}} = 0.9\text{V}$	40	70	150	310	430	$\mu\text{A}$

**Table 18. Dual-Supply Operation Fixed  $V_{\text{DDIO}}$  Current Consumption SLEEP Mode  
 $f_{\text{sys\_osc}} = \text{IPO}$**

PARAMETER	SYMBOL	COMMON CONDITIONS	CONDITIONS	TYPICAL					UNITS
				-40°C	25°C	55°C	85°C	105°C	
$V_{\text{DDIO}}$ Current, SLEEP Mode	$I_{\text{DDIO\_FSLPD}}$	Fixed, IPO enabled, total current into $V_{\text{DDIO}}$ and $V_{\text{DDA}}$ pins, $V_{\text{DDIO}} = 3.3\text{V}$ , CPU in SLEEP mode, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPCTRL. ovr = 0b10, internal regulator set to 1.1V	355	385	400	420	430	$\mu\text{A}$
			PWRSEQ_LPCTRL. ovr = 0b01, internal regulator set to 1.0V	355	385	400	420	430	$\mu\text{A}$
			PWRSEQ_LPCTRL. ovr = 0b00, internal regulator set to 0.9V	355	385	400	420	430	$\mu\text{A}$
		Fixed, IPO enabled, total current into $V_{\text{DDIO}}$ and $V_{\text{DDA}}$ pins, $V_{\text{DDIO}} = 1.8\text{V}$ , CPU in SLEEP mode, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPCTRL. ovr = 0b10, internal regulator set to 1.1V	340	370	385	400	415	$\mu\text{A}$
			PWRSEQ_LPCTRL. ovr = 0b01, internal regulator set to 1.0V	340	370	385	400	415	$\mu\text{A}$
			PWRSEQ_LPCTRL. ovr = 0b00, internal regulator set to 0.9V	340	370	385	400	415	$\mu\text{A}$

Dual-Supply ACTIVE Mode  $f_{\text{SYS\_OSC}} = \text{IBRO}$

**Table 19. Dual-Supply Operation Fixed  $V_{\text{CORE}}$  Current Consumption ACTIVE Mode  
 $f_{\text{SYS\_OSC}} = \text{IBRO}$**

PARAMETER	SYMBOL	COMMON CONDITIONS	CONDITIONS	TYPICAL					UNITS
				-40°C	25°C	55°C	85°C	105°C	
$V_{\text{CORE}}$ Current, ACTIVE Mode	$I_{\text{CORE\_FACTD}}$	Fixed, IBRO enabled, total current into $V_{\text{CORE}}$ pin, CPU in ACTIVE mode 0MHz operation, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPCTR L.ovr = 0b10, $V_{\text{CORE}} = 1.1\text{V}$	40	105	225	465	690	$\mu\text{A}$
			PWRSEQ_LPCTR L.ovr = 0b01, $V_{\text{CORE}} = 1.0\text{V}$	30	80	175	370	560	$\mu\text{A}$
			PWRSEQ_LPCTR L.ovr = 0b00, $V_{\text{CORE}} = 0.9\text{V}$	20	55	120	270	410	$\mu\text{A}$

**Table 20. Dual-Supply Operation Fixed  $V_{\text{DDIO}}$  Current Consumption ACTIVE Mode  
 $f_{\text{SYS\_OSC}} = \text{IBRO}$**

PARAMETER	SYMBOL	COMMON CONDITIONS	CONDITIONS	TYPICAL					UNITS
				-40°C	25°C	55°C	85°C	105°C	
$V_{\text{DDIO}}$ Current, ACTIVE Mode	$I_{\text{DDIO\_FACTD}}$	Fixed, IBRO enabled, total current into $V_{\text{DDIO}}$ and $V_{\text{DDA}}$ pins, $V_{\text{DDIO}} = 3.3\text{V}$ , CPU in ACTIVE mode 0MHz operation, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPCTRL.ovr = 0b10, internal regulator set to 1.1V	105	115	120	125	130	$\mu\text{A}$
			PWRSEQ_LPCTRL.ovr = 0b01, internal regulator set to 1.0V	105	115	120	125	130	$\mu\text{A}$
			PWRSEQ_LPCTRL.ovr = 0b00, internal regulator set to 0.9V	105	115	120	125	130	$\mu\text{A}$
		Fixed, IBRO enabled, total current into $V_{\text{DDIO}}$ and $V_{\text{DDA}}$ pins, $V_{\text{DDIO}} = 1.8\text{V}$ , CPU in ACTIVE mode 0MHz operation, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPCTRL.ovr = 0b10, internal regulator set to 1.1V	85	90	95	100	105	$\mu\text{A}$
			PWRSEQ_LPCTRL.ovr = 0b01, internal regulator set to 1.0V	85	90	95	100	105	$\mu\text{A}$
			PWRSEQ_LPCTRL.ovr = 0b00, internal regulator set to 0.9V	85	90	95	100	105	$\mu\text{A}$



Dual-Supply SLEEP Mode  $f_{\text{sys\_osc}} = \text{IBRO}$

**Table 21. Dual-Supply Operation Fixed  $V_{\text{CORE}}$  Current Consumption SLEEP Mode  
 $f_{\text{sys\_osc}} = \text{IBRO}$**

PARAMETER	SYMBOL	COMMON CONDITIONS	CONDITIONS	TYPICAL					UNITS
				-40°C	25°C	55°C	85°C	105°C	
$V_{\text{CORE}}$ Current, SLEEP Mode	$I_{\text{CORE\_FSLPD}}$	Fixed, IBRO enabled, total current into $V_{\text{CORE}}$ pin, CPU in SLEEP mode, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPCTRL. ovr = 0b10, $V_{\text{CORE}} = 1.1\text{V}$	190	250	380	645	830	$\mu\text{A}$
			PWRSEQ_LPCTRL. ovr = 0b01, $V_{\text{CORE}} = 1.0\text{V}$	100	145	255	465	620	$\mu\text{A}$
			PWRSEQ_LPCTRL. ovr = 0b00, $V_{\text{CORE}} = 0.9\text{V}$	40	70	150	310	430	$\mu\text{A}$

**Table 22. Dual-Supply Operation Fixed  $V_{\text{DDIO}}$  Current Consumption SLEEP Mode  
 $f_{\text{sys\_osc}} = \text{IBRO}$**

PARAMETER	SYMBOL	COMMON CONDITIONS	CONDITIONS	TYPICAL					UNITS
				-40°C	25°C	55°C	85°C	105°C	
$V_{\text{DDIO}}$ Current, SLEEP Mode	$I_{\text{DD\_FSLPD}}$	Fixed, IBRO enabled, total current into $V_{\text{DDIO}}$ and $V_{\text{DDA}}$ pins, $V_{\text{DDIO}} = 3.3\text{V}$ , CPU in SLEEP mode, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPCTRL. ovr = 0b10, internal regulator set to 1.1V	105	115	120	125	130	$\mu\text{A}$
			PWRSEQ_LPCTRL. ovr = 0b01, internal regulator set to 1.0V	105	115	120	125	130	$\mu\text{A}$
			PWRSEQ_LPCTRL. ovr = 0b00, internal regulator set to 0.9V	105	115	120	125	130	$\mu\text{A}$
		Fixed, IBRO enabled, total current into $V_{\text{DDIO}}$ and $V_{\text{DDA}}$ pins, $V_{\text{DDIO}} = 1.8\text{V}$ , CPU in SLEEP mode, inputs tied to $V_{\text{SS}}$ or $V_{\text{DDIO}}$ , outputs source/sink 0mA	PWRSEQ_LPCTRL. ovr = 0b10, internal regulator set to 1.1V	85	90	95	100	105	$\mu\text{A}$
			PWRSEQ_LPCTRL. ovr = 0b01, internal regulator set to 1.0V	85	90	95	100	105	$\mu\text{A}$
			PWRSEQ_LPCTRL. ovr = 0b00, internal regulator set to 0.9V	85	90	95	100	105	$\mu\text{A}$

Dual-Supply DEEPSLEEP Mode

**Table 23. Dual-Supply Operation Fixed  $V_{CORE}$  Current Consumption DEEPSLEEP Mode**

PARAMETER	SYMBOL	COMMON CONDITIONS	CONDITIONS	TYPICAL					UNITS
				-40°C	25°C	55°C	85°C	105°C	
$V_{CORE}$ Fixed Current, DEEPSLEEP Mode	$I_{CORE\_FDSLDP}$	$V_{DDIO} = 3.3V, V_{CORE} = 1.1V$	PWRSEQ_LPCTRL. fastwk_en = 0, PWRSEQ_LPCTRL. bg_dis = 0	3.4	6.8	15.4	36	54	$\mu A$
		$V_{DDIO} = 3.3V, V_{CORE} = 0.855V$	PWRSEQ_LPCTRL. fastwk_en = 0, PWRSEQ_LPCTRL. bg_dis = 0	0.9	2.7	8	22	35	$\mu A$
		$V_{DDIO} = 1.8V, V_{CORE} = 1.1V$	PWRSEQ_LPCTRL. fastwk_en = 0, PWRSEQ_LPCTRL. bg_dis = 0	3.4	6.8	15	36	54	$\mu A$
		$V_{DDIO} = 1.8V, V_{CORE} = 0.855V$	PWRSEQ_LPCTRL. fastwk_en = 0, PWRSEQ_LPCTRL. bg_dis = 0	0.9	2.7	8	22	35	$\mu A$

**Table 24. Dual-Supply Operation Fixed  $V_{DDIO}$  Current Consumption DEEPSLEEP Mode**

PARAMETER	SYMBOL	COMMON CONDITIONS	CONDITIONS	TYPICAL					UNITS
				-40°C	25°C	55°C	85°C	105°C	
$V_{DDIO}$ Fixed Current, DEEPSLEEP Mode	$I_{DDIO\_FDSLDP}$	$V_{DDIO} = 3.3V, V_{CORE} = 1.1V$	PWRSEQ_LPCTRL. fastwk_en = 0, PWRSEQ_LPCTRL. bg_dis = 0	0.1	0.19	0.4	0.9	1.5	$\mu A$
		$V_{DDIO} = 3.3V, V_{CORE} = 0.855V$	PWRSEQ_LPCTRL. fastwk_en = 0, PWRSEQ_LPCTRL. bg_dis = 0	0.1	0.19	0.4	0.9	1.5	$\mu A$
		$V_{DDIO} = 1.8V, V_{CORE} = 1.1V$	PWRSEQ_LPCTRL. fastwk_en = 0, PWRSEQ_LPCTRL. bg_dis = 0	0.015	0.05	0.17	0.55	1	$\mu A$
		$V_{DDIO} = 1.8V, V_{CORE} = 0.855V$	PWRSEQ_LPCTRL. fastwk_en = 0, PWRSEQ_LPCTRL. bg_dis = 0	0.015	0.05	0.17	0.55	1	$\mu A$

Dual-Supply BACKUP Mode

**Table 25. Dual-Supply Operation Fixed  $V_{CORE}$  Current Consumption BACKUP Mode**

PARAMETER	SYMBOL	COMMON CONDITIONS	CONDITIONS	TYPICAL					UNITS
				-40°C	25°C	55°C	85°C	105°C	
$V_{CORE}$ Fixed Current, BACKUP Mode	$I_{CORE\_FBKUD}$	0KB SRAM retained with RTC disabled, retention regulator disabled.	$V_{DDIO} = 3.3V,$ $V_{CORE} = 1.1V$	0.3	0.33	1	3.1	5.15	$\mu A$
			$V_{DDIO} = 3.3V,$ $V_{CORE} = 0.855V$	0.07	0.18	0.7	2.45	4.2	$\mu A$
			$V_{DDIO} = 1.8V,$ $V_{CORE} = 1.1V$	0.3	0.33	1	3.05	5.15	$\mu A$
			$V_{DDIO} = 1.8V,$ $V_{CORE} = 0.855V$	0.07	0.18	0.7	2.45	4.2	$\mu A$
		20KB SRAM retained with RTC disabled	$V_{DDIO} = 3.3V,$ $V_{CORE} = 1.1V$	0.8	1.28	2.95	7.5	11.5	$\mu A$
			$V_{DDIO} = 3.3V,$ $V_{CORE} = 0.855V$	0.2	0.54	1.7	5.05	8.3	$\mu A$
			$V_{DDIO} = 1.8V,$ $V_{CORE} = 1.1V$	0.8	1.28	2.95	7.5	11.5	$\mu A$
			$V_{DDIO} = 1.8V,$ $V_{CORE} = 0.855V$	0.2	0.54	1.7	5.05	8.3	$\mu A$
		40KB SRAM retained with RTC disabled	$V_{DDIO} = 3.3V,$ $V_{CORE} = 1.1V$	1.3	2.23	4.95	11.9	18	$\mu A$
			$V_{DDIO} = 3.3V,$ $V_{CORE} = 0.855V$	0.32	0.9	2.7	7.7	12.5	$\mu A$
			$V_{DDIO} = 1.8V,$ $V_{CORE} = 1.1V$	1.3	2.23	4.95	11.9	18	$\mu A$
			$V_{DDIO} = 1.8V,$ $V_{CORE} = 0.855V$	0.32	0.9	2.7	7.7	12.5	$\mu A$
		60KB SRAM retained with RTC disabled	$V_{DDIO} = 3.3V,$ $V_{CORE} = 1.1V$	1.85	3.2	6.85	16	24	$\mu A$
			$V_{DDIO} = 3.3V,$ $V_{CORE} = 0.855V$	0.45	1.25	3.65	10	16	$\mu A$
			$V_{DDIO} = 1.8V,$ $V_{CORE} = 1.1V$	1.85	3.2	6.85	16	24	$\mu A$
			$V_{DDIO} = 1.8V,$ $V_{CORE} = 0.855V$	0.45	1.25	3.65	10	16	$\mu A$
		80KB SRAM retained with RTC disabled	$V_{DDIO} = 3.3V,$ $V_{CORE} = 1.1V$	2.35	4.1	8.8	20.5	30	$\mu A$
			$V_{DDIO} = 3.3V,$ $V_{CORE} = 0.855V$	0.6	1.6	4.6	12.7	20	$\mu A$
			$V_{DDIO} = 1.8V,$ $V_{CORE} = 1.1V$	2.35	4.1	8.8	20.5	30	$\mu A$
			$V_{DDIO} = 1.8V,$ $V_{CORE} = 0.855V$	0.6	1.6	4.6	12.7	20	$\mu A$

**Table 26. Dual-Supply Operation Fixed  $V_{DDIO}$  Current Consumption BACKUP Mode**

PARAMETER	SYMBOL	COMMON CONDITIONS	CONDITIONS	TYPICAL					UNITS
				-40°C	25°C	55°C	85°C	105°C	
	$I_{DDIO\_FBKUD}$	0KB SRAM retained with	$V_{DDIO} = 3.3V,$ $V_{CORE} = 1.1V$	0.09	0.19	0.4	0.93	1.45	$\mu A$

PARAMETER	SYMBOL	COMMON CONDITIONS	CONDITIONS	TYPICAL					UNITS
				-40°C	25°C	55°C	85°C	105°C	
V <sub>DDIO</sub> Fixed Current, BACKUP Mode		RTC disabled, retention regulator disabled.	V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 0.855V	0.09	0.19	0.4	0.93	1.45	μA
			V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 1.1V	0.013	0.05	0.17	0.55	0.96	μA
			V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 0.855V	0.013	0.05	0.17	0.55	0.96	μA
		20KB SRAM retained with RTC disabled	V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 1.1V	0.09	0.19	0.4	0.93	1.45	μA
			V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 0.855V	0.09	0.19	0.4	0.93	1.45	μA
			V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 1.1V	0.013	0.05	0.17	0.55	0.96	μA
			V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 0.855V	0.013	0.05	0.17	0.55	0.96	μA
		40KB SRAM retained with RTC disabled	V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 1.1V	0.09	0.19	0.4	0.93	1.45	μA
			V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 0.855V	0.09	0.19	0.4	0.93	1.45	μA
			V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 1.1V	0.013	0.05	0.17	0.55	0.96	μA
			V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 0.855V	0.013	0.05	0.17	0.55	0.96	μA
		60KB SRAM retained with RTC disabled	V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 1.1V	0.09	0.19	0.4	0.93	1.45	μA
			V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 0.855V	0.09	0.19	0.4	0.93	1.45	μA
			V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 1.1V	0.013	0.05	0.17	0.55	0.96	μA
			V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 0.855V	0.013	0.05	0.17	0.55	0.96	μA
		80KB SRAM retained with RTC disabled	V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 1.1V	0.09	0.19	0.4	0.93	1.45	μA
			V <sub>DDIO</sub> = 3.3V, V <sub>CORE</sub> = 0.855V	0.09	0.19	0.4	0.93	1.45	μA
			V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 1.1V	0.013	0.05	0.17	0.55	0.96	μA
			V <sub>DDIO</sub> = 1.8V, V <sub>CORE</sub> = 0.855V	0.013	0.05	0.17	0.55	0.96	μA

Dual-Supply STORAGE Mode

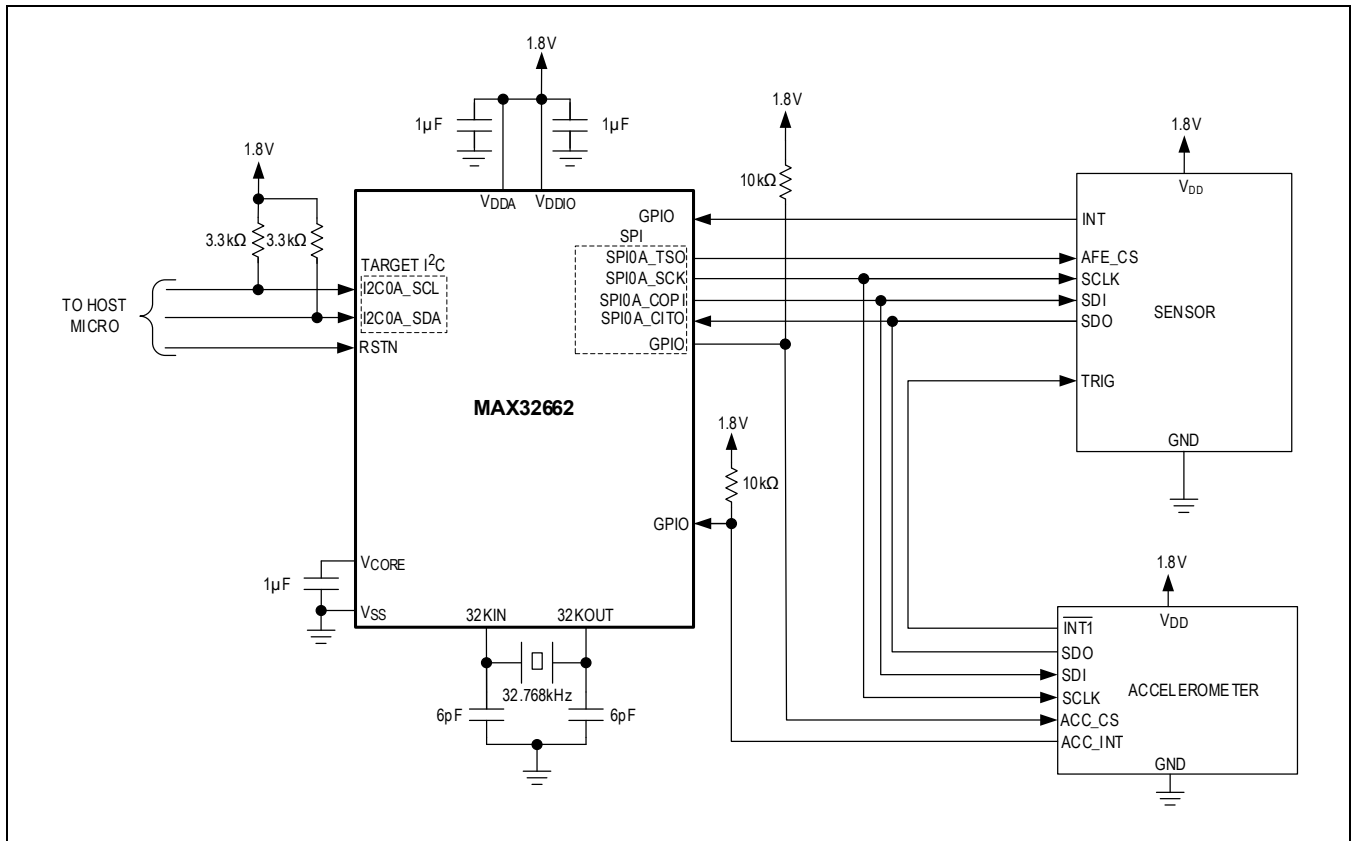
**Table 27. Dual-Supply Operation Fixed  $V_{CORE}$  Current Consumption STORAGE Mode**

PARAMETER	SYMBOL	CONDITIONS	TYPICAL					UNITS
			-40°C	25°C	55°C	85°C	105°C	
$V_{CORE}$ Fixed Current, STORAGE Mode	$I_{CORE\_FSTOD}$	$V_{DDIO} = 3.3V,$ $V_{CORE} = 1.1V$	0.3	0.33	1	3.05	5.15	$\mu A$
		$V_{DDIO} = 3.3V,$ $V_{CORE} = 0.855V$	0.07	0.18	0.72	2.45	4.2	$\mu A$
		$V_{DDIO} = 1.8V,$ $V_{CORE} = 1.1V$	0.3	0.33	1	3.05	5.15	$\mu A$
		$V_{DDIO} = 1.8V,$ $V_{CORE} = 0.855V$	0.07	0.18	0.72	2.45	4.2	$\mu A$

**Table 28. Dual-Supply Operation Fixed  $V_{DDIO}$  Current Consumption STORAGE Mode**

PARAMETER	SYMBOL	CONDITIONS	TYPICAL					UNITS
			-40°C	25°C	55°C	85°C	105°C	
$V_{DDIO}$ Fixed Current, STORAGE Mode	$I_{DDIO\_FSTOD}$	$V_{DDIO} = 3.3V,$ $V_{CORE} = 1.1V$	0.11	0.22	0.45	1.1	1.7	$\mu A$
		$V_{DDIO} = 3.3V,$ $V_{CORE} = 0.855V$	0.11	0.22	0.45	1.1	1.7	$\mu A$
		$V_{DDIO} = 1.8V,$ $V_{CORE} = 1.1V$	0.02	0.06	0.19	0.65	1.11	$\mu A$
		$V_{DDIO} = 1.8V,$ $V_{CORE} = 0.855V$	0.02	0.06	0.19	0.65	1.11	$\mu A$

Typical Application Circuits



## Ordering Information

PART NUMBER	SCPBL	SWD	TMR	LPTMR	I <sup>2</sup> C	SPI	CMP	12-BIT SAR ADC INPUTS	UART	GPIO	PIN-PACKAGE
MAX32662GTJ+	No	Yes	3	1	2	2	2	4	2	21	32 TQFN-EP, 5mm x 5mm x 0.5mm pitch
MAX32662GTJ+T	No	Yes	3	1	2	2	2	4	2	21	32 TQFN-EP, 5mm x 5mm x 0.5mm pitch
MAX32662GTJBL+*	Yes	Yes	3	1	2	2	2	4	2	21	32 TQFN-EP, 5mm x 5mm x 0.5mm pitch
MAX32662GTJBL+T*	Yes	Yes	3	1	2	2	2	4	2	21	32 TQFN-EP, 5mm x 5mm x 0.5mm pitch
MAX32662GWP+*	No	Yes	3	1	2	2	2	4	2	12	20 WLP, 2.30mm x 1.92mm x 0.4mm pitch
MAX32662GWP+T*	No	Yes	3	1	2	2	2	4	2	12	20 WLP, 2.30mm x 1.92mm x 0.4mm pitch
MAX32662GWPBL+*	Yes	Yes	3	1	2	2	2	4	2	12	20 WLP, 2.30mm x 1.92mm x 0.4mm pitch
MAX32662GWPBL+T*	Yes	Yes	3	1	2	2	2	4	2	12	20 WLP, 2.30mm x 1.92mm x 0.4mm pitch

All packages contain CAN 2.0B, I<sup>2</sup>S, and four PT.

SWD = serial wire debug; TMR = timer; LPTMR = low-power timer; CMP = comparator; PT = pulse train

+ Denotes a lead(Pb)-free/RoHS-compliant package.

T = Tape and reel.

\* Future product—contact factory for availability.

## Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	1/23	Initial release	—

