

## **Data sheet for SINAMICS G120X**

6SL3220-1YH40-0AP0 Article No.:

Client order no. : Order no.: Offer no. : Remarks :

Rated data Input 3 АС Number of phases 500 ... 690 V +10 % -20 % Line voltage 47 ... 63 Hz Line frequency Rated voltage 690V IEC 600V NEC Rated current (LO) 59.00 A 59.00 A Rated current (HO) 54.40 A 54.40 A Output Number of phases 3 AC Rated voltage **690V IEC** 600V NEC 1) Rated power (LO) 55.00 kW 60.00 hp 45.00 kW Rated power (HO) 50.00 hp Rated current (LO) 62.00 A 62.00 A Rated current (HO) 52.00 A 52.00 A Rated current (IN) 64.00 A Max. output current 84.00 A Pulse frequency 2 kHz Output frequency for vector control 0 ... 200 Hz Output frequency for V/f control 0 ... 550 Hz Overload capability

Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

Communication

150% x base load current IH for 60 s within a 600 s cycle time

General tech. specifications		
Power factor λ	0.90 0.95	
Offset factor $\cos\phi$	0.99	
Efficiency η	0.98	
Sound pressure level (1m)	70 dB	
Power loss 3)	1.360 kW	
Filter class (integrated)	RFI suppression filter for Category C2	
EMC category (with accessories)	Category C2	
Safety function "Safe Torque Off"	without SIRIUS device (e.g. via S7- 1500F)	
Communication		

Error: No CAD-Data available for this configuration.

Item no.: Consignment no. : Project :

Figure similar

Inputs / outputs		
Standard digital inputs		
Number	6	
Switching level: $0 \rightarrow 1$	11 V	
Switching level: $1 \rightarrow 0$	5 V	
Max. inrush current	15 mA	
Fail-safe digital inputs		
Number	1	
Digital outputs		
Number as relay changeover contact	2	
Output (resistive load)	DC 30 V, 5.0 A	
Number as transistor	0	
Analog / digital inputs		
Number	2 (Differential input)	
Number Resolution	2 (Differential input) 10 bit	
Resolution	·	
Resolution	·	
Resolution  Switching threshold as digital input	10 bit	
Resolution  Switching threshold as digital input $0 \rightarrow 1$ $1 \rightarrow 0$	10 bit 4 V	
Resolution  Switching threshold as digital input $0 \rightarrow 1$ $1 \rightarrow 0$	10 bit 4 V	
Resolution  Switching threshold as digital input  0 → 1  1 → 0  Analog outputs  Number	10 bit 4 V 1.6 V	
Resolution  Switching threshold as digital input  0 → 1  1 → 0  Analog outputs  Number  PTC/ KTY interface	10 bit 4 V 1.6 V 1 (Non-isolated output)	
Resolution  Switching threshold as digital input  0 → 1  1 → 0  Analog outputs  Number  PTC/ KTY interface  1 motor temperature sensor input, ser Thermo-Click, accuracy ±5 °C	10 bit 4 V 1.6 V 1 (Non-isolated output)	
Resolution  Switching threshold as digital input  0 → 1  1 → 0  Analog outputs  Number  PTC/ KTY interface  1 motor temperature sensor input, ser Thermo-Click, accuracy ±5 °C  Closed-loop col	10 bit  4 V  1.6 V  1 (Non-isolated output)  nsors that can be connected PTC, KTY are	
Resolution  Switching threshold as digital input  0 → 1  1 → 0  Analog outputs  Number  PTC/ KTY interface  1 motor temperature sensor input, ser Thermo-Click, accuracy ±5 °C  Closed-loop con  W/f linear / square-law / parameterizable	10 bit  4 V  1.6 V  1 (Non-isolated output)  nsors that can be connected PTC, KTY are natively techniques	
Resolution  Switching threshold as digital input  0 → 1  1 → 0  Analog outputs  Number  PTC/ KTY interface  1 motor temperature sensor input, ser Thermo-Click, accuracy ±5 °C  Closed-loop col  W/f linear / square-law / parameterizable  W/f with flux current control (FCC)	10 bit  4 V  1.6 V  1 (Non-isolated output)  nsors that can be connected PTC, KTY are ntrol techniques  Yes	
Resolution  Switching threshold as digital input  0 → 1  1 → 0  Analog outputs  Number  PTC/ KTY interface  1 motor temperature sensor input, sent Thermo-Click, accuracy ±5 °C  Closed-loop could be control of the co	10 bit  4 V  1.6 V  1 (Non-isolated output)  nsors that can be connected PTC, KTY are national techniques  Yes  Yes	
Resolution  Switching threshold as digital input  0 → 1  1 → 0  Analog outputs  Number  PTC/ KTY interface  1 motor temperature sensor input, ser Thermo-Click, accuracy ±5 °C  Closed-loop cor  W/f linear / square-law / parameterizable  W/f with flux current control (FCC)  W/f ECO linear / square-law  Sensorless vector control	10 bit  4 V  1.6 V  1 (Non-isolated output)  nsors that can be connected PTC, KTY are ntrol techniques  Yes  Yes  Yes	
Resolution  Switching threshold as digital input  0 → 1  1 → 0  Analog outputs  Number  PTC/ KTY interface  1 motor temperature sensor input, ser Thermo-Click, accuracy ±5 °C	10 bit  4 V  1.6 V  1 (Non-isolated output)  nsors that can be connected PTC, KTY are ntrol techniques  Yes  Yes  Yes  Yes	

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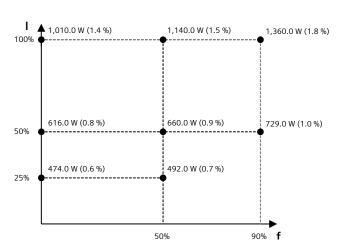
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Ambient conditions		
Standard board coating type	Class 3C2, according to IEC 60721-3-3: 2002	
Cooling	Air cooling using an integrated fan	
Cooling air requirement	0.083 m³/s (2.931 ft³/s)	
Installation altitude	1,000 m (3,280.84 ft)	
Ambient temperature		
Operation	-20 45 °C (-4 113 °F)	
Transport	-40 70 °C (-40 158 °F)	
Storage	-25 55 °C (-13 131 °F)	
Relative humidity		
Max. operation	95~% At 40 °C (104 °F), condensation and icing not permissible	
Co	onnections	
Signal cable		
Conductor cross-section	0.15 1.50 mm <sup>2</sup> (AWG 24 AWG 16)	
Line side		
Version	screw-type terminal	
Conductor cross-section	25.00 70.00 mm <sup>2</sup> (AWG 6 AWG 3/0)	
Motor end		
Version	Screw-type terminals	
Conductor cross-section	25.00 70.00 mm <sup>2</sup> (AWG 6 AWG 3/0)	
DC link (for braking resistor)		
PE connection	Screw-type terminals	
Max. motor cable length		
Shielded	100 m (328.08 ft)	

Mechanical data		
Degree of protection	IP20 / UL open type	
Frame size	FSE	
Net weight	28.7 kg (63.27 lb)	
Dimensions		
Width	275 mm (10.83 in)	
Height	551 mm (21.69 in)	
Depth	248 mm (9.76 in)	
Standards		
Compliance with standards	UL, cUL, CE, C-Tick (RCM), EAC, KCC, SEMI F47, REACH	
CE marking	EMC Directive 2004/108/EC, Low- Voltage Directive 2006/95/EC	

Converter losses to IEC61800-9-2*		
Efficiency class	IE2	
Comparison with the reference converter (90% / 100%)	39.2 %	



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

\*converted values

<sup>1)</sup> The output current and HP ratings are valid for the voltage range 550V-600V

<sup>&</sup>lt;sup>3)</sup>Typical value. More information can be found in the element group "Converter losses to IEC 61800-9-2" in this datasheet.